

$$\text{IM1)} \frac{1}{3} \left( \frac{4}{1+i} - \frac{5}{2-i} \right) = \frac{1}{3} \cdot \frac{8-4i-5-5i}{(1+i)(2-i)} = \frac{1}{3} \cdot \frac{3-9i}{3+i} \cdot \frac{3-i}{3-i} = \frac{1}{3} \cdot \frac{9-9-30i}{9+1} = -i.$$

$$-i = \cos\left(\frac{3}{2}\pi\right) + i \operatorname{sen}\left(\frac{3}{2}\pi\right).$$

$$\sqrt[3]{-i} = \cos\left(\frac{\pi}{2} + k \cdot \frac{2\pi}{3}\right) + i \operatorname{sen}\left(\frac{\pi}{2} + k \cdot \frac{2\pi}{3}\right); 0 \leq k \leq 2.$$

$$\text{Per } k=0: \cos\frac{\pi}{2} + i \operatorname{sen}\frac{\pi}{2} = i; \text{ per } k=1: \cos\frac{7}{6}\pi + i \operatorname{sen}\frac{7}{6}\pi = -\frac{\sqrt{3}}{2} - i \cdot \frac{1}{2};$$

$$\text{per } k=2: \cos\frac{11}{6}\pi + i \operatorname{sen}\frac{11}{6}\pi = \frac{\sqrt{3}}{2} - i \cdot \frac{1}{2}.$$

$$z_1 \cdot z_2 \cdot z_3 = \cos\left(\frac{\pi}{2} + \frac{7}{6}\pi + \frac{11}{6}\pi\right) + i \operatorname{sen}\left(\frac{\pi}{2} + \frac{7}{6}\pi + \frac{11}{6}\pi\right) = \cos\frac{21}{6}\pi + i \operatorname{sen}\frac{21}{6}\pi = \\ = \cos\frac{7}{2}\pi + i \operatorname{sen}\frac{7}{2}\pi = \cos\frac{3}{2}\pi + i \operatorname{sen}\frac{3}{2}\pi = -i.$$

$$\text{IM2)} A = \begin{vmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{vmatrix} \rightarrow \begin{vmatrix} 1-\lambda & 0 & 0 & 1 \\ 0 & 1-\lambda & 0 & 0 \\ 0 & 0 & 1-\lambda & 0 \\ 1 & 0 & 0 & 1-\lambda \end{vmatrix} = (1-\lambda) \begin{vmatrix} 1-\lambda & 0 & 1 \\ 0 & 1-\lambda & 0 \\ 1 & 0 & 1-\lambda \end{vmatrix} = (1-\lambda)^2 \begin{vmatrix} 1-\lambda & 1 \\ 1 & 1-\lambda \end{vmatrix} =$$

$$= (1-\lambda)^2 ((1-\lambda)^2 - 1) = (1-\lambda)^2 (\lambda^2 - 2\lambda) = \lambda \cdot (1-\lambda)^2 (\lambda-2) = 0 \Rightarrow \lambda_1 = 0; \lambda_2 = \lambda_3 = 1; \lambda_4 = 2.$$

$$\text{Per } \lambda = 0: \|A - 0I\| \cdot X = \underline{0} \Rightarrow \begin{cases} x_1 + x_4 = 0 \\ x_2 = 0 \\ x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_4 = -x_1 \\ x_2 = 0 \\ x_3 = 0 \end{cases} \text{ Autovetture: } (1; 0; 0; -1)$$

$$\text{Per } \lambda = 1: \|A - 1I\| \cdot X = \underline{0} \Rightarrow \begin{cases} x_4 = 0 \\ x_1 = 0 \end{cases} \Rightarrow (0; x_2; x_3; 0) \begin{cases} \rightarrow (0; 1; 0; 0) \\ \rightarrow (0; 0; 1; 0) \end{cases}$$

$$\text{Per } \lambda = 2: \|A - 2I\| \cdot X = \underline{0} \Rightarrow \begin{cases} -x_1 + x_4 = 0 \\ -x_2 = 0 \\ -x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_4 = x_1 \\ x_2 = 0 \\ x_3 = 0 \end{cases} \text{ Autovetture: } (1; 0; 0; 1).$$

$$\text{Autovettori: } (1; 0; 0; -1) \rightarrow \left(\frac{1}{\sqrt{2}}; 0; 0; -\frac{1}{\sqrt{2}}\right); (1; 0; 0; 1) \rightarrow \left(\frac{1}{\sqrt{2}}; 0; 0; \frac{1}{\sqrt{2}}\right).$$

$$U = \begin{vmatrix} \frac{1}{\sqrt{2}} & 0 & 0 & \frac{1}{\sqrt{2}} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\frac{1}{\sqrt{2}} & 0 & 0 & \frac{1}{\sqrt{2}} \end{vmatrix}; U^T \cdot A \cdot U = \begin{vmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{vmatrix}.$$

$$\text{IM3)} \left\| \begin{array}{ccc|c} 1 & 2 & 1 & 1 \\ -2 & 1 & 3 & 1 \\ 2 & -1 & k & m \end{array} \right\| \rightarrow \left\| \begin{array}{ccc|c} 1 & 2 & 1 & 1 \\ 0 & 5 & 5 & 3 \\ 0 & -5 & k-2 & m-2 \end{array} \right\| \rightarrow \left\| \begin{array}{ccc|c} 1 & 2 & 1 & 1 \\ 0 & 5 & 5 & 3 \\ 0 & 0 & k+3 & m+1 \end{array} \right\|$$

$R_2 \leftarrow R_2 + 2R_1$        $R_3 \leftarrow R_3 + R_2$   
 $R_3 \leftarrow R_3 - 2R_1$

Se  $k+3=0 \Rightarrow k=-3$  e  $m+1=0 \Rightarrow m=-1$ :  $\operatorname{Car}(A) = 2 = \operatorname{Car}(A|Y)$ :  $\infty^1$  soluzioni.

Se  $k+3 \neq 0$ ;  $k \neq -3$ ;  $\forall m$ :  $\operatorname{Car}(A) = 3 = \operatorname{Car}(A|Y)$ : 1 sola soluzione.

Se  $k = -3$  e  $m+1 \neq 0$ :  $m \neq -1$ :  $\operatorname{Car}(A) = 2 < \operatorname{Car}(A|Y) = 3$ : nessuna soluzione.

Se  $k = -3$  i tre vettori sono un insieme di generatrici di un sottospazio di dimensione 2; se  $k \neq -3$  i tre vettori sono una base di  $\mathbb{R}^3$ .

I14)  $\begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} \cdot \begin{vmatrix} x & y \\ z & w \end{vmatrix} = \begin{vmatrix} x & y \\ z & w \end{vmatrix} \cdot \begin{vmatrix} 3 & 2 \\ 4 & 2 \end{vmatrix} : A \cdot P = P \cdot B$

$$\begin{cases} x + 2z = 3x + 4y \\ y + 2w = 2x + 2y \\ 3x + 4z = 3z + 4w \\ 3y + 4w = 2z + 2w \end{cases} \Rightarrow \begin{cases} 2x = 2z - 4y \\ y = 2w - 2x \\ z = 4w - 3x \\ 2w = 2z - 3y \end{cases} \Rightarrow \begin{cases} x = z - 2y = z - \frac{4}{3}z + \frac{4}{3}w = \frac{4}{3}w - \frac{1}{3}z \\ y = 2w - 2z + 4y \Rightarrow y = \frac{2}{3}z - \frac{2}{3}w \\ z = 4w - 3z + 4z - 4w \Rightarrow 0 = 0 \\ 2w = 2z - 2z + 2w \Rightarrow 0 = 0 \end{cases} \Rightarrow$$

$\Rightarrow \begin{vmatrix} \frac{4}{3}w - \frac{1}{3}z & \frac{2}{3}z - \frac{2}{3}w \\ z & w \end{vmatrix} = P$ . Se  $z = w = 3 \Rightarrow \begin{vmatrix} 3 & 0 \\ 3 & 3 \end{vmatrix} = P$ .

I15)  $|A| = \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & k \end{vmatrix} = \begin{vmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 1 & -k & k \end{vmatrix} = k \cdot \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} = k \neq 0$ ; se  $k \neq 0$  esiste  $A^{-1}$ .

Se  $|A^{-1}| = \frac{1}{3} \Rightarrow |A| = k = 3$ .

$$\begin{aligned} &\begin{vmatrix} 1 & 1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 1 & 0 & 3 & | & 0 & 0 & 1 \end{vmatrix} \rightarrow \begin{vmatrix} 1 & 1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & -1 & 2 & | & -1 & 0 & 1 \end{vmatrix} \rightarrow \begin{vmatrix} 1 & 1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & 3 & | & -1 & 1 & 1 \end{vmatrix} \rightarrow \\ &\rightarrow \begin{vmatrix} 1 & 1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{vmatrix} \rightarrow \begin{vmatrix} 1 & 1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 0 & | & \frac{1}{3} & \frac{2}{3} & -\frac{1}{3} \\ 0 & 0 & 1 & | & -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{vmatrix} \rightarrow \begin{vmatrix} 1 & 0 & 0 & | & 1 & -\frac{1}{3} & 0 \\ 0 & 1 & 0 & | & \frac{1}{3} & \frac{2}{3} & -\frac{1}{3} \\ 0 & 0 & 1 & | & -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{vmatrix} \end{aligned}$$

Quindi  $A^{-1} = \begin{vmatrix} 1 & -1 & 0 \\ \frac{1}{3} & \frac{2}{3} & -\frac{1}{3} \\ -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{vmatrix}$ .