

IM1) $x^3 + 2x^2 + 4x + 8 = 0$ if $x = -2$: $-8 + 8 - 8 + 8 = 0$

$x^3 + 2x^2 + 4x + 8 = (x+2)(x^2+4) = 0 \Rightarrow$

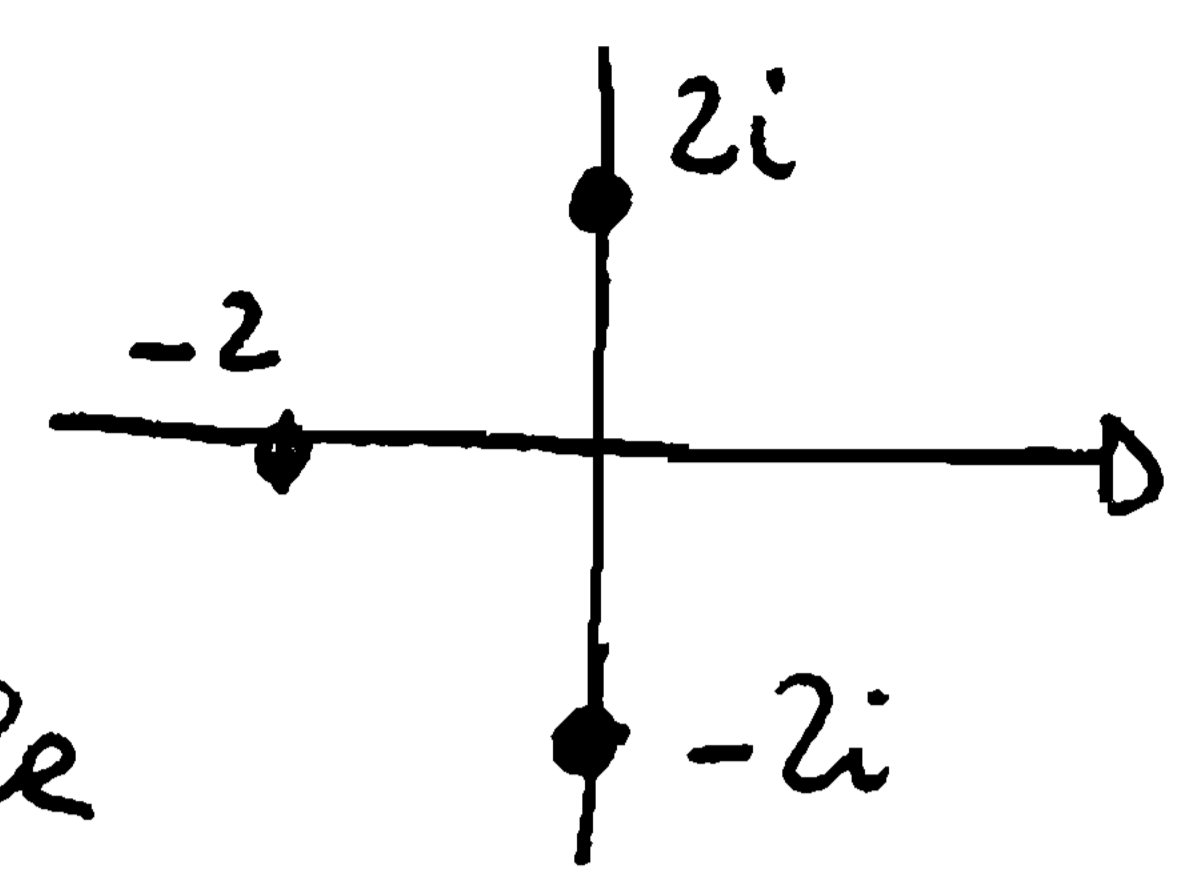
$\Rightarrow x_1 = -2; x_2 = 2i; x_3 = -2i.$

Representing the points in the complex plane we get:

so they are not the vertices of an equilateral triangle

inscribed in a circle with center at the origin \Rightarrow they are not the three third order roots of a complex number.

$$\begin{array}{ccc|c} 1 & 2 & 4 & 8 \\ -2 & -2 & 0 & -8 \\ \hline 1 & 0 & 4 & 0 \end{array}$$



IM2) $A \cdot P = P \cdot B \Rightarrow \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \cdot \begin{pmatrix} x_1 & y_1 \\ x_2 & y_2 \end{pmatrix} = \begin{pmatrix} x_1 & y_1 \\ x_2 & y_2 \end{pmatrix} \cdot \begin{pmatrix} -3 & -3 \\ 8 & 7 \end{pmatrix} \Rightarrow$

$$\Rightarrow \begin{cases} 5x_1 + x_2 - 8y_1 + 0y_2 = 0 \\ 3x_1 + 0x_2 - 5y_1 + y_2 = 0 \\ x_1 + 5x_2 + 0y_1 - 8y_2 = 0 \\ 0x_1 + 3x_2 + y_1 - 5y_2 = 0 \end{cases} \Rightarrow \begin{pmatrix} 5 & 1 & -8 & 0 \\ 3 & 0 & -5 & 1 \\ 1 & 5 & 0 & -8 \\ 0 & 3 & 1 & -5 \end{pmatrix} \Rightarrow \begin{pmatrix} 15 & 0 & -8 \\ 0 & 3 & 1 & -5 \\ 5 & 1 & -8 & 0 \\ 3 & 0 & -5 & 1 \end{pmatrix} \Rightarrow$$

$$\begin{cases} 2x_1 + x_2 = -3x_1 + 8y_1 \\ 2y_1 + y_2 = -3x_1 + 7y_1 \\ x_1 + 2x_2 = -3x_2 + 8y_2 \\ y_1 + 2y_2 = -3x_2 + 7y_2 \end{cases} \Rightarrow$$

$$\Rightarrow \begin{pmatrix} 15 & 0 & -8 \\ 0 & 3 & 1 & -5 \\ 0 & -24 & -8 & 40 \\ 0 & -15 & -5 & 25 \end{pmatrix} \Rightarrow \begin{pmatrix} 15 & 0 & -8 \\ 0 & 3 & 1 & -5 \\ 0 & 3 & 1 & -5 \\ 0 & 3 & 1 & -5 \end{pmatrix} \Rightarrow \begin{pmatrix} 15 & 0 & -8 \\ 0 & 3 & 1 & -5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{array}{l} R_3 \leftarrow R_3 - 5R_1 \\ R_4 \leftarrow R_4 - 3R_1 \end{array} \quad \begin{array}{l} R_3 \leftarrow -\frac{1}{8}R_3 \\ R_4 \leftarrow -\frac{1}{5}R_4 \end{array} \quad \begin{array}{l} R_3 \leftarrow R_3 - R_2 \\ R_4 \leftarrow R_4 - R_2 \end{array}$$

So the RANK = 2 and the system has ∞^2 solutions.

A and B are similar matrices.

IM3) $\begin{cases} x_1 - 2x_2 + 2x_3 + x_4 = -1 \\ 2x_1 + 3x_2 + x_3 + x_4 = 2 \\ x_1 - 9x_2 + mx_3 + Kx_4 = h \end{cases} \Rightarrow \begin{pmatrix} 1 & -2 & 2 & 1 & | & -1 \\ 2 & 3 & 1 & 1 & | & 2 \\ 1 & -9 & m & K & | & h \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & -2 & 2 & 1 & | & -1 \\ 0 & 7 & -3 & -1 & | & 4 \\ 0 & -7 & m-2 & K-1 & | & h+1 \end{pmatrix} \Rightarrow$

$$\Rightarrow \begin{pmatrix} 1 & -2 & 2 & 1 & | & -1 \\ 0 & 7 & -3 & -1 & | & 4 \\ 0 & 0 & m-5 & K-2 & | & h+5 \end{pmatrix}$$

$$R_2 \leftarrow R_2 - 2R_1; R_3 \leftarrow R_3 - R_1$$

$$R_3 \leftarrow R_3 + R_2$$

If $m=5$ and $K=2$ and $h=-5$: $RANK(A) = 2 = RANK(A|Y) \Rightarrow \infty^2$ Solutions

If $m \neq 5$ or $K \neq 2$ $\forall h$: $RANK(A) = 3 = RANK(A|Y) \Rightarrow \infty^1$ Solutions

If $m=5$ and $K=2$ but $h \neq -5$: $RANK(A) = 2 < 3 = RANK(A|Y) \Rightarrow$ no solutions.

IM4) $A \cdot X_1 = \underline{0}; A \cdot X_2 = \underline{0}; A \cdot X_3 = Y_1. A = \begin{pmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{pmatrix}$

$$\begin{pmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{cases} a_1 = 0 \\ a_2 = 0 \\ a_3 = 0 \end{cases}$$

$$\begin{pmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{cases} b_1 + c_1 = 0 \\ b_2 + c_2 = 0 \\ b_3 + c_3 = 0 \end{cases} \Rightarrow \begin{cases} b_1 = -c_1 \\ b_2 = -c_2 \\ b_3 = -c_3 \end{cases} \Rightarrow A = \begin{pmatrix} 0 & -c_1 & c_1 \\ 0 & -c_2 & c_2 \\ 0 & -c_3 & c_3 \end{pmatrix}$$

$$\begin{pmatrix} 0 & -c_1 & c_1 \\ 0 & -c_2 & c_2 \\ 0 & -c_3 & c_3 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ -3 \\ -6 \end{pmatrix} \Rightarrow \begin{cases} -2c_1 - c_1 = -3c_1 = 3 \Rightarrow c_1 = -1 \Rightarrow b_1 = 1 \\ -2c_2 - c_2 = -3c_2 = -3 \Rightarrow c_2 = 1 \Rightarrow b_2 = -1 \\ -2c_3 - c_3 = -3c_3 = -6 \Rightarrow c_3 = 2 \Rightarrow b_3 = -2 \end{cases}$$

$$A = \begin{pmatrix} 0 & 1 & -1 \\ 0 & -1 & 1 \\ 0 & -2 & 2 \end{pmatrix} \rightarrow \begin{vmatrix} -\lambda & 1 & -1 \\ 0 & -1-\lambda & 1 \\ 0 & -2 & 2-\lambda \end{vmatrix} = (-\lambda) \left((-1-\lambda)(2-\lambda) + 2 \right) = -\lambda (\lambda^2 - \lambda - 2 + 2) = -\lambda^2 (\lambda - 1) = 0$$

$\lambda_1 = \lambda_2 = 0; \lambda_3 = 1.$

Fr $\lambda = 0$ $\|A - 0 \cdot I\| = \begin{vmatrix} 0 & 1 & -1 \\ 0 & -1 & 1 \\ 0 & -2 & 2 \end{vmatrix} \rightarrow \begin{vmatrix} 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{vmatrix} : \text{RANK}(A - 0I) = 1 \Rightarrow \mu_0^f = 3 - 1 = \mu_0^g$

so the matrix is a diagonalizable one.

II M1) $f(x,y) = \begin{cases} \frac{x^2}{x+y} : x \neq -y \\ 0 : x = -y \end{cases}$. $\partial_r f(0;0) = \lim_{t \rightarrow 0} \frac{f((0;0) + t(\cos \alpha; \sin \alpha)) - f(0;0)}{t} =$
 $= \lim_{t \rightarrow 0} \left(\frac{t^2 \cos^2 \alpha}{t \cos \alpha + t \sin \alpha} - 0 \right) \cdot \frac{1}{t} = \lim_{t \rightarrow 0} \frac{t^2 \cos^2 \alpha}{t^2 (\cos \alpha + \sin \alpha)} = \frac{\cos^2 \alpha}{\cos \alpha + \sin \alpha}$

The derivative exists if $\cos \alpha + \sin \alpha \neq 0 \Rightarrow \cos \alpha \neq -\sin \alpha \Rightarrow x \neq -y$.

If $\cos \alpha = -\sin \alpha \Leftrightarrow x = -y : \lim_{t \rightarrow 0} \frac{f((0;0) + tv) - f(0;0)}{t} = \lim_{t \rightarrow 0} \frac{0}{t} = 0$.

The function has directional derivative $\forall v$.

II M2) $\begin{cases} f(x,y,z) = xyz - e^{x-y} = 0 \\ g(x,y,z) = xyz - e^{y-z} = 0 \end{cases} ; \begin{cases} f(1;1;1) = 0 \\ g(1;1;1) = 0 \end{cases}$

$$\frac{\partial(f;g)}{\partial(x,y,z)} = \begin{vmatrix} yz - e^{x-y} & xz + e^{x-y} & xy \\ yz & xz - e^{y-z} & xy + e^{y-z} \end{vmatrix} ; \frac{\partial(f;g)}{\partial(x,y,z)}(1;1;1) = \begin{vmatrix} 0 & 2 & 1 \\ 1 & 0 & 2 \end{vmatrix}$$

Since $\begin{vmatrix} 2 & 1 \\ 0 & 2 \end{vmatrix} = 4 \neq 0$ the implicit function $x \rightarrow (y(x); z(x))$ exists.

$$\frac{dy}{dx} = - \frac{\begin{vmatrix} 0 & 1 \\ 1 & 2 \end{vmatrix}}{\begin{vmatrix} 2 & 1 \\ 0 & 2 \end{vmatrix}} = - \frac{-1}{4} = \frac{1}{4} ; \frac{dz}{dx} = - \frac{\begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix}}{\begin{vmatrix} 2 & 1 \\ 0 & 2 \end{vmatrix}} = - \frac{2}{4} = -\frac{1}{2}$$

Equation of the tangent line at $x=1 : (1;1) + x \cdot \left(\frac{1}{4} i - \frac{1}{2} j \right) \Rightarrow X \rightarrow \left(1 + \frac{1}{4}x ; 1 - \frac{1}{2}x \right)$.

$$\text{II M3)} \begin{cases} \text{Max/min } f(x,y) = x-y \\ \text{s.t. } \begin{cases} x^2 - 2x - y + 1 \leq 0 \\ x^2 - 2x + y - 1 \leq 0 \end{cases} \end{cases}$$

$$g_1: y = x^2 - 2x + 1 = (x-1)^2$$

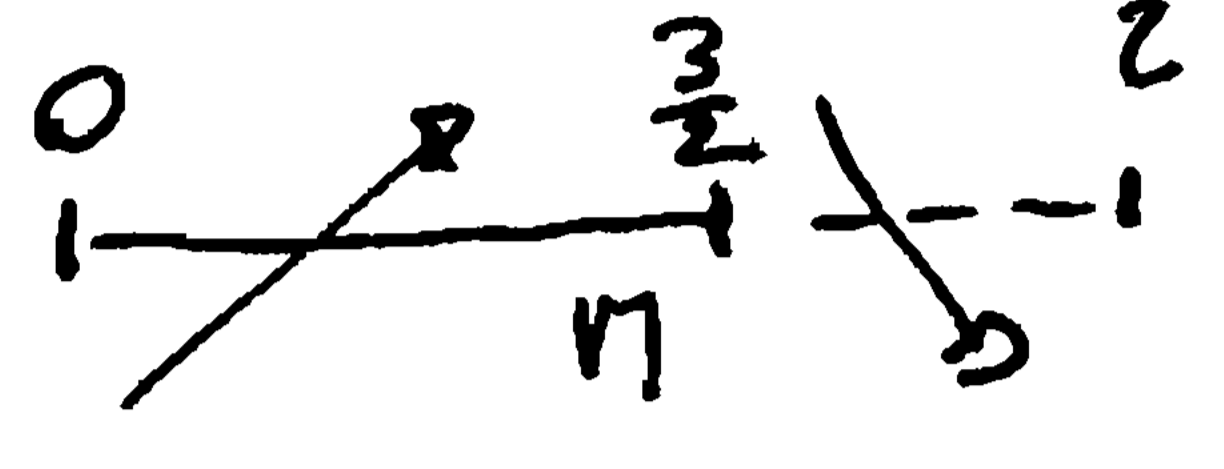
$$g_2: y = -x^2 + 2x + 1 = -(x-1)^2 + 2$$

$$(x-1)^2 = 2 - (x-1)^2 \Rightarrow (x-1)^2 = 1 \Rightarrow x-1 = \pm 1 \Rightarrow$$

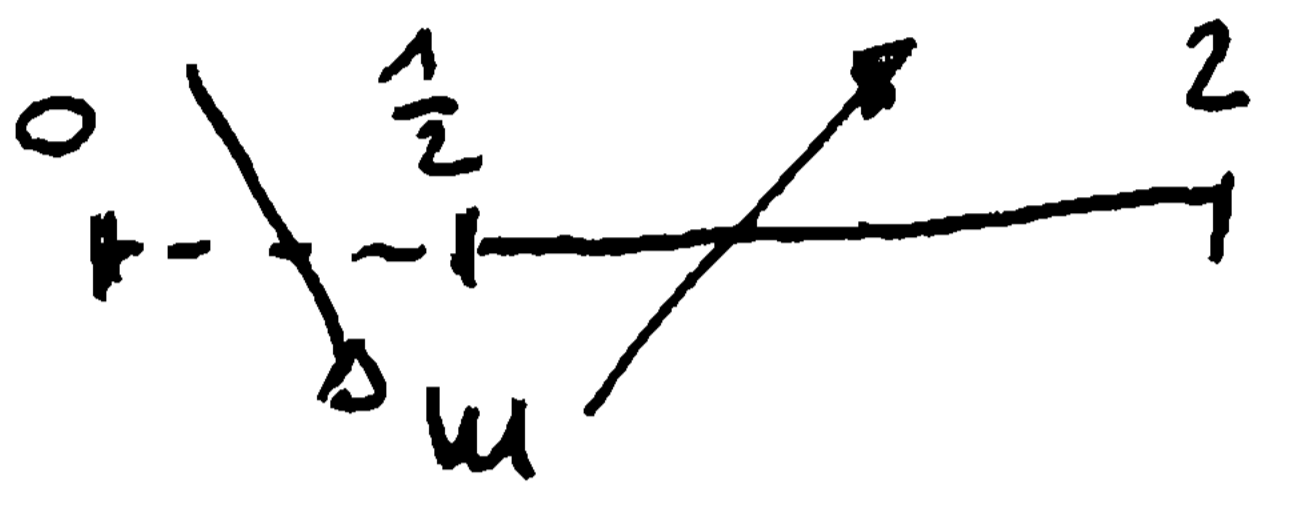
$$\rightarrow \begin{cases} x=2 \\ y=1 \end{cases} \text{ and } \begin{cases} x=0 \\ y=1 \end{cases}$$

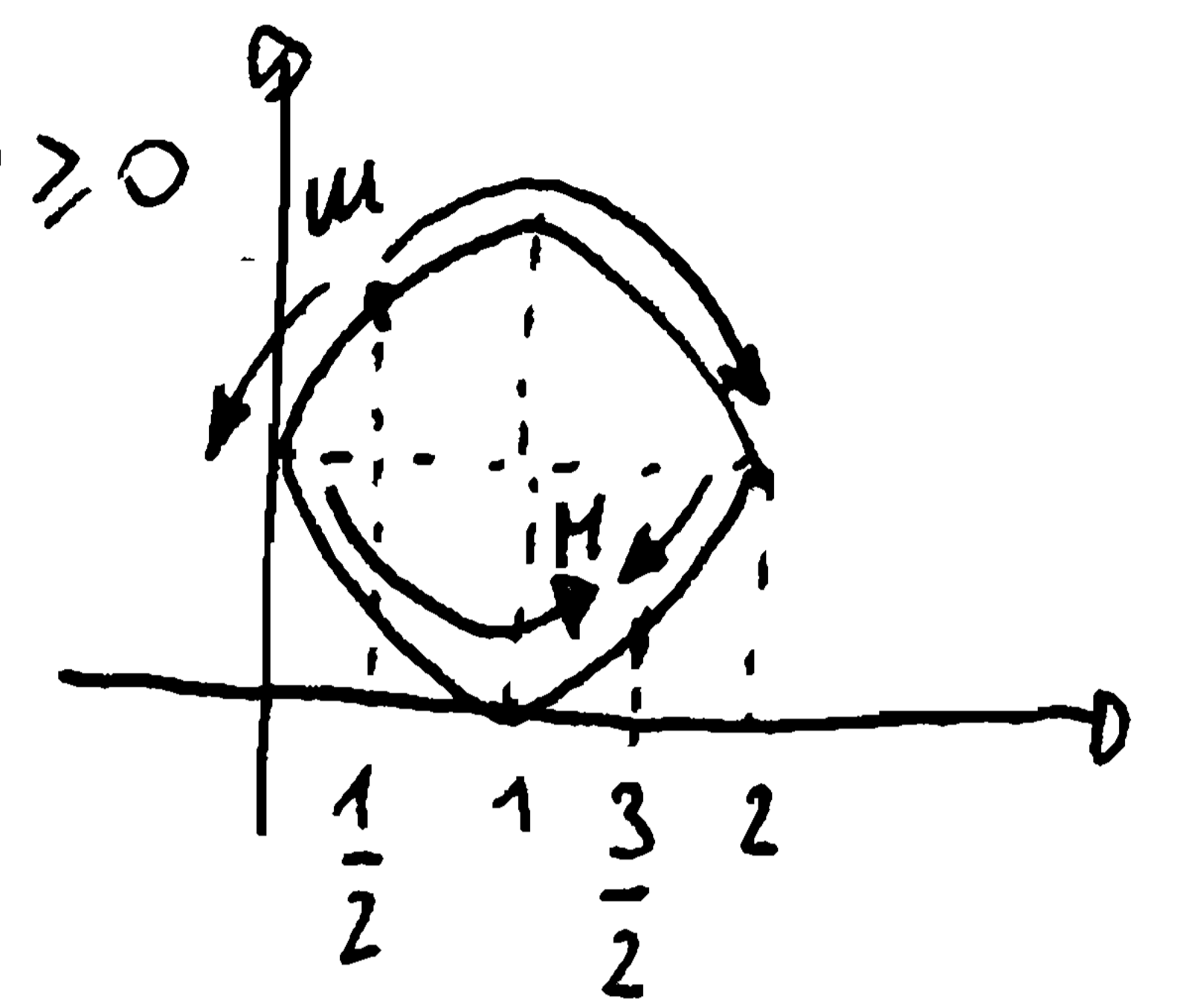
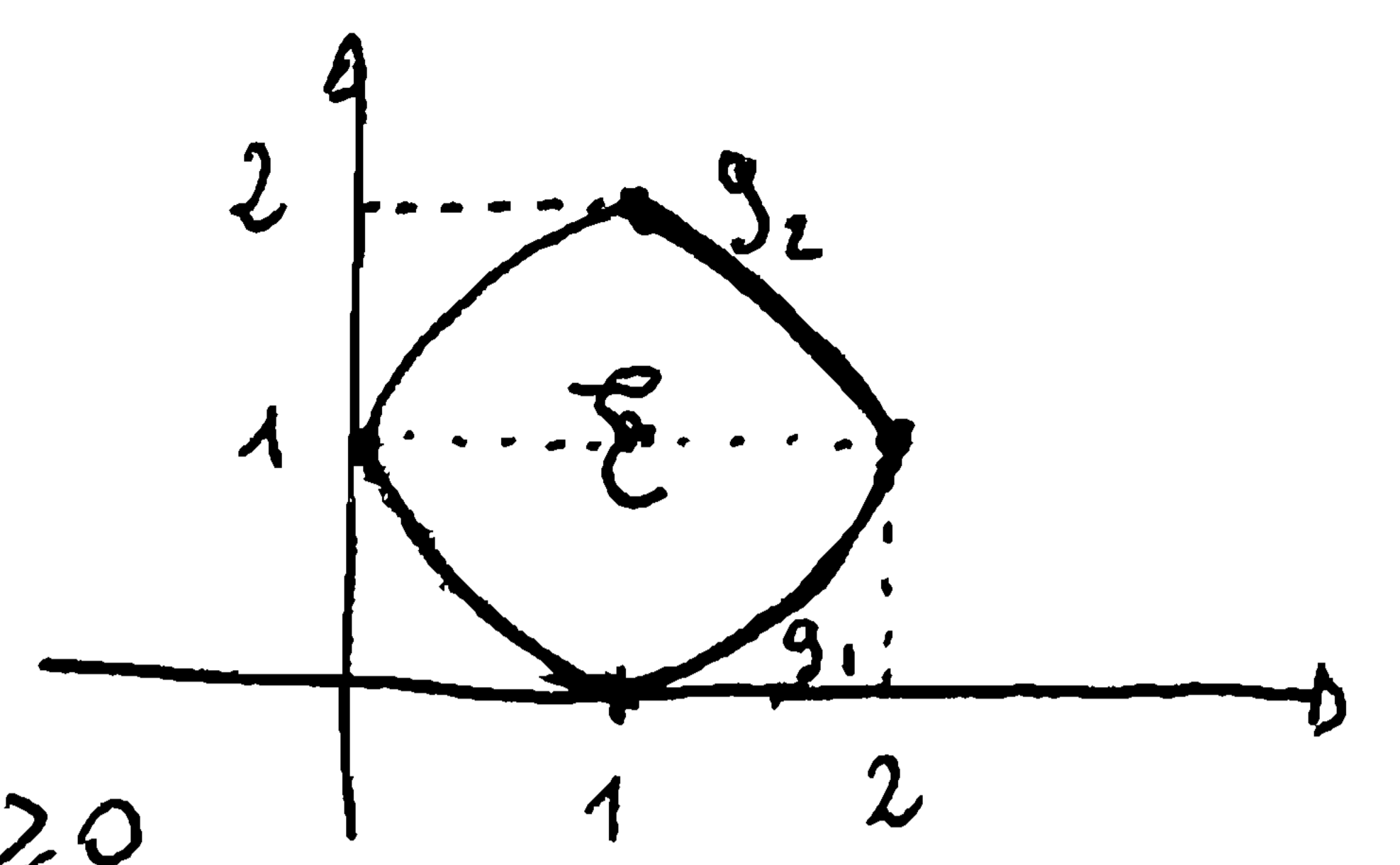
$\nabla f = (1, -1) \Rightarrow$ no free stationary points.

$$\text{If } y = (x-1)^2 \Rightarrow f(x) = x - (x-1)^2 \Rightarrow f'(x) = 1 - 2(x-1) \geq 0$$

$$\Rightarrow 2x \leq 3 \Rightarrow x \leq \frac{3}{2}$$


$$\text{If } y = 2 - (x-1)^2 \Rightarrow f(x) = x - 2 + (x-1)^2 \Rightarrow f'(x) = 1 + 2(x-1) \geq 0$$

$$\Rightarrow 2x \geq 1 \Rightarrow x \geq \frac{1}{2}$$




At the point $x = \frac{1}{2}; y = \frac{7}{4}; f(\frac{1}{2}; \frac{7}{4}) = -\frac{5}{4}$: absolute minimum

At the point $x = \frac{3}{2}; y = \frac{1}{4}; f(\frac{3}{2}; \frac{1}{4}) = \frac{5}{4}$: absolute maximum.

$$\text{II M4)} \begin{cases} \text{Max/min } f(x,y,z) = xy - z \\ \text{s.t.: } xz + yz = 4 \end{cases} \cdot \Lambda = xy - z - \lambda(xz + yz - 4)$$

$$\begin{cases} \Lambda'_x = y - \lambda z = 0 \\ \Lambda'_y = x - \lambda z = 0 \\ \Lambda'_z = -1 - \lambda x - \lambda y = 0 \\ xz + yz = 4 \end{cases} \Rightarrow \begin{cases} y = \lambda z \\ x = \lambda z \Rightarrow y = x \\ 2\lambda x = -1 \Rightarrow x = -\frac{1}{2\lambda} \\ xz + yz = 4 \end{cases} \Rightarrow \begin{cases} x = -\frac{1}{2\lambda} \\ y = -\frac{1}{2\lambda} \\ z = \frac{1}{\lambda} \cdot x = -\frac{1}{2\lambda^2} \\ -\frac{1}{2\lambda} \cdot (-\frac{1}{2\lambda^2}) + (-\frac{1}{2\lambda}) \cdot (-\frac{1}{2\lambda^2}) = 4 \end{cases} \Rightarrow$$

$$\Rightarrow \frac{2}{4\lambda^3} = 4 \Rightarrow \lambda^3 = \frac{1}{8} \Rightarrow \lambda = \frac{1}{2} \Rightarrow \begin{cases} x = -1 \\ y = -1 \\ z = -2 \\ \lambda = \frac{1}{2} \end{cases} \quad \bar{H} = \begin{vmatrix} 0 & z & z & x+y \\ z & 0 & 1 & -\lambda \\ z & 1 & 0 & -\lambda \\ x+y & -\lambda & -\lambda & 0 \end{vmatrix}$$

$$|\bar{H}_3(-1, -1, -2; \frac{1}{2})| = \begin{vmatrix} 0 & -2 & -2 \\ -2 & 0 & 1 \\ -2 & 1 & 0 \end{vmatrix} = \begin{vmatrix} 0 & -2 & -2 \\ 0 & -1 & 1 \\ -2 & 1 & 0 \end{vmatrix} = (-2) \begin{vmatrix} -2 & -2 \\ -1 & 1 \end{vmatrix} = (-2)(-4) = 8 > 0. \text{ (MAX??)}$$

$$|\bar{H}_4(-1, -1, -2; \frac{1}{2})| = \begin{vmatrix} 0 & -2 & -2 & -2 \\ -2 & 0 & 1 & -\frac{1}{2} \\ -2 & 1 & 0 & -\frac{1}{2} \\ -2 & -\frac{1}{2} & -\frac{1}{2} & 0 \end{vmatrix} = \begin{vmatrix} 0 & -2 & -2 & -2 \\ 0 & -1 & 1 & 0 \\ -2 & 1 & 0 & -\frac{1}{2} \\ 0 & -\frac{3}{2} & -\frac{1}{2} & \frac{1}{2} \end{vmatrix} = (-2) \begin{vmatrix} -2 & -2 & -2 \\ -1 & 1 & 0 \\ -\frac{3}{2} & -\frac{1}{2} & \frac{1}{2} \end{vmatrix} = (-2) \begin{vmatrix} -4 & -2 & -2 \\ 0 & 1 & 0 \\ -2 & -\frac{1}{2} & \frac{1}{2} \end{vmatrix} =$$

$$= (-2)(1) \begin{vmatrix} -4 & -2 \\ -2 & \frac{1}{2} \end{vmatrix} = (-2) \cdot (-2 - 4) = 12 > 0$$
 : The point $(-1, -1, -2)$ is a

saddle point, so the problem has no solutions.