

TASK MATHEMATICS for ECONOMIC APPLICATIONS 17/2/2015 MFEA1

IM1)  $e^{\log 2 + \frac{5}{3}\pi i} = e^{\log 2} \cdot e^{\frac{5}{3}\pi i} = 2 \cdot (\cos \frac{5}{3}\pi + i \sin \frac{5}{3}\pi) = 2 \cdot (\frac{1}{2} - \frac{\sqrt{3}}{2}i) = 1 - \sqrt{3}i.$

$\sqrt[3]{z} = \sqrt[3]{2} \cdot (\cos(\frac{5}{9}\pi + k \cdot \frac{2\pi}{3}) + i \sin(\frac{5}{9}\pi + k \cdot \frac{2\pi}{3})); 0 \leq k \leq 2.$

$k=0: \sqrt[3]{2} (\cos \frac{5}{9}\pi + i \sin \frac{5}{9}\pi); k=1: \sqrt[3]{2} (\cos \frac{11}{9}\pi + i \sin \frac{11}{9}\pi); k=2: \sqrt[3]{2} (\cos \frac{17}{9}\pi + i \sin \frac{17}{9}\pi).$

IM2)  $f(x_1; x_2; x_3; x_4) = (x_1 + x_4; 2x_1 + x_2 + x_3; x_1 + x_2 + x_3 - x_4).$

$$f(x) = \begin{pmatrix} 1 & 0 & 0 & 1 \\ 2 & 1 & 1 & 0 \\ 1 & 1 & 1 & -1 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 \\ 2 & 1 & 1 & 0 \\ 1 & 1 & 1 & -1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & -2 \\ 0 & 1 & 1 & -2 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & -2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$R_2 \leftarrow R_2 - 2R_1$        $R_3 \leftarrow R_3 - R_2$   
 $R_3 \leftarrow R_3 - R_1$

$RANK(A) = 2 \Rightarrow \dim(\text{Im}) = 2$  and  $\dim(\text{Ker}) = 4 - 2 = 2.$

Basis for Kernel:  $A \cdot X = \underline{0} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & -2 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{cases} x_1 + x_4 = 0 \\ x_2 + x_3 - 2x_4 = 0 \end{cases} \Rightarrow$

$\Rightarrow \begin{cases} x_4 = -x_1 \\ x_2 + x_3 + 2x_1 = 0 \end{cases} \Rightarrow \begin{cases} x_4 = -x_1 \\ x_3 = -2x_1 - x_2 \end{cases} \Rightarrow (x_1; x_2; -2x_1 - x_2; -x_1) \begin{cases} (1; 0; -2; -1) \text{ BASIS} \\ (0; 1; -1; 0) \text{ KERNEL} \end{cases}$

Basis for Image:  $\begin{pmatrix} 1 & 0 & 0 & 1 & | & y_1 \\ 2 & 1 & 1 & 0 & | & y_2 \\ 1 & 1 & 1 & -1 & | & y_3 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 & | & y_1 \\ 0 & 1 & 1 & -2 & | & y_2 - 2y_1 \\ 0 & 1 & 1 & -2 & | & y_3 - y_1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 & | & y_1 \\ 0 & 1 & 1 & -2 & | & y_2 - 2y_1 \\ 0 & 0 & 0 & 0 & | & y_3 - y_2 + y_1 \end{pmatrix}$

We use the same elementary operations.

So we need:  $y_3 - y_2 + y_1 = 0 \Rightarrow y_3 = y_2 - y_1 \Rightarrow (y_1; y_2; y_2 - y_1) \begin{cases} (1; 0; -1) \text{ BASIS} \\ (0; 1; 1) \text{ IMAGE} \end{cases}$

IM3)  $A = \begin{pmatrix} 1 & 0 & k \\ 0 & 1 & 0 \\ k & 0 & 1 \end{pmatrix} \Rightarrow \begin{vmatrix} 1-\lambda & 0 & k \\ 0 & 1-\lambda & 0 \\ k & 0 & 1-\lambda \end{vmatrix} = (1-\lambda) \cdot ((1-\lambda)^2 - k^2) = (1-\lambda)(\lambda^2 - 2\lambda + 1 - k^2) = 0.$

If  $\lambda = 1$  is a multiple eigenvalue:  $1 - 2 + 1 - k^2 \Rightarrow k^2 = 0 \Rightarrow k = 0. A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I_3.$

$P_3(\lambda) = (1-\lambda) \cdot (\lambda^2 - 2\lambda + 1) = -(\lambda-1)^3 \Rightarrow \lambda_1 = \lambda_2 = \lambda_3 = 1.$

We must find three orthogonal eigenvectors for  $\lambda = 1$  and  $k = 0.$

Since the matrix  $A = \mathbb{I}_3$ , the orthogonal matrix is the matrix  $A$  itself, as  $\mathbb{I}_3 \cdot A \cdot \mathbb{I}_3 = \mathbb{I}_3$  and  $\mathbb{I}_3 = D$ : diagonal matrix.

$$\text{IM4)} \quad A = \begin{vmatrix} 3 & 0 & 5 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{vmatrix} \cdot |A| = 1 \cdot \begin{vmatrix} 3 & 5 \\ 1 & 2 \end{vmatrix} = 1 \cdot (6 - 5) = 1.$$

$$\begin{vmatrix} 3 & 0 & 5 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{vmatrix} \xrightarrow{\text{Adj}} \begin{vmatrix} 2 & 0 & -1 \\ 0 & 1 & 0 \\ -5 & 0 & 3 \end{vmatrix}^T \begin{vmatrix} 2 & 0 & -5 \\ 0 & 1 & 0 \\ -1 & 0 & 3 \end{vmatrix} = A^{-1}.$$

$$\begin{vmatrix} 3 & 0 & 5 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{vmatrix} \cdot \begin{vmatrix} x_1 \\ x_2 \\ x_3 \end{vmatrix} = \begin{vmatrix} 2 \\ -1 \\ 3 \end{vmatrix} \Rightarrow \begin{vmatrix} x_1 \\ x_2 \\ x_3 \end{vmatrix} = \begin{vmatrix} 3 & 0 & 5 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{vmatrix}^{-1} \cdot \begin{vmatrix} 2 \\ -1 \\ 3 \end{vmatrix} = \begin{vmatrix} 2 & 0 & -5 \\ 0 & 1 & 0 \\ -1 & 0 & 3 \end{vmatrix} \cdot \begin{vmatrix} 2 \\ -1 \\ 3 \end{vmatrix} = \begin{vmatrix} -11 \\ -1 \\ 7 \end{vmatrix}.$$

II M1)  $f(x; y) = x^2 - xy^2$ : differentiable function of the second order.

$$\nabla f(x; y) = (2x - y^2; -2xy). \quad H(x; y) = \begin{vmatrix} 2 & -2y \\ -2y & -2x \end{vmatrix}. \quad u = \left(\frac{1}{\sqrt{2}}; \frac{1}{\sqrt{2}}\right); \quad v = \left(\frac{1}{\sqrt{2}}; -\frac{1}{\sqrt{2}}\right).$$

$$\mathcal{D}_u f(x; y) = \nabla f(x; y) \cdot u = (2x - y^2; -2xy) \cdot \left(\frac{1}{\sqrt{2}}; \frac{1}{\sqrt{2}}\right) = \frac{1}{\sqrt{2}} (2x - y^2 - 2xy).$$

$$\begin{aligned} \mathcal{D}_{u,v}^2 f(x; y) &= u \cdot H \cdot v^T = \begin{vmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{vmatrix} \cdot \begin{vmatrix} 2 & -2y \\ -2y & -2x \end{vmatrix} \cdot \begin{vmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{vmatrix} = \begin{vmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{vmatrix} \cdot \begin{vmatrix} \frac{1}{\sqrt{2}}(2+2y) \\ \frac{1}{\sqrt{2}}(-2y+2x) \end{vmatrix} = \\ &= \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} \cdot (2+2y-2y+2x) = \frac{1}{2} (2+2x) = 1+x. \end{aligned}$$

$$\text{So we get the system: } \begin{cases} \frac{1}{\sqrt{2}} (2x - y^2 - 2xy) = \sqrt{2} \\ 1+x = 2 \end{cases} \Rightarrow \begin{cases} 2x - y^2 - 2xy = 2 \\ 1+x = 2 \end{cases} \Rightarrow \begin{cases} y^2 + 2y = 0 \\ x = 1 \end{cases} \Rightarrow$$

$$\Rightarrow \begin{cases} x = 1 \\ y(y+2) = 0 \end{cases} \Rightarrow \begin{cases} x = 1 \\ y = 0 \end{cases} \text{ and } \begin{cases} x = 1 \\ y = -2 \end{cases}. \text{ We find two points: } P_1 = (1; 0) \text{ and } P_2 = (1; -2).$$

II M2)  $f(x; y) = y \log x - x e^y + x = 0$ ;  $f(1; 0) = 0 - 1 + 1 = 0$ .

$$\nabla f(x; y) = \left(y \cdot \frac{1}{x} - e^y + 1; \log x - x e^y\right); \quad \nabla f(1; 0) = (0 - 1 + 1; 0 - 1) = (0; -1).$$

$f'_y(1; 0) \neq 0$  so exists  $x: x \rightarrow y(x)$  implicit function.

$$y'(1) = - \frac{f'_x(1;0)}{f'_y(1;0)} = - \frac{0}{-1} = 0.$$

$$H(f(x;y)) = \begin{vmatrix} -y \cdot \frac{1}{x^2} & \frac{1}{x} - e^y \\ \frac{1}{x} - e^y & -x e^y \end{vmatrix}; \quad H(f(1;0)) = \begin{vmatrix} 0 & 0 \\ 0 & -1 \end{vmatrix}.$$

$$y''(1) = - \frac{f''_{xx}(1;0) + 2f''_{xy}(1;0) \cdot y' + f''_{yy}(1;0) \cdot (y')^2}{f'_y(1;0)} = - \frac{0 + 2 \cdot 0 \cdot 0 + (-1) \cdot (0)^2}{-1} = 0.$$

PM 3)  $f(x;y) = x^2 - xy^2 + kxy.$

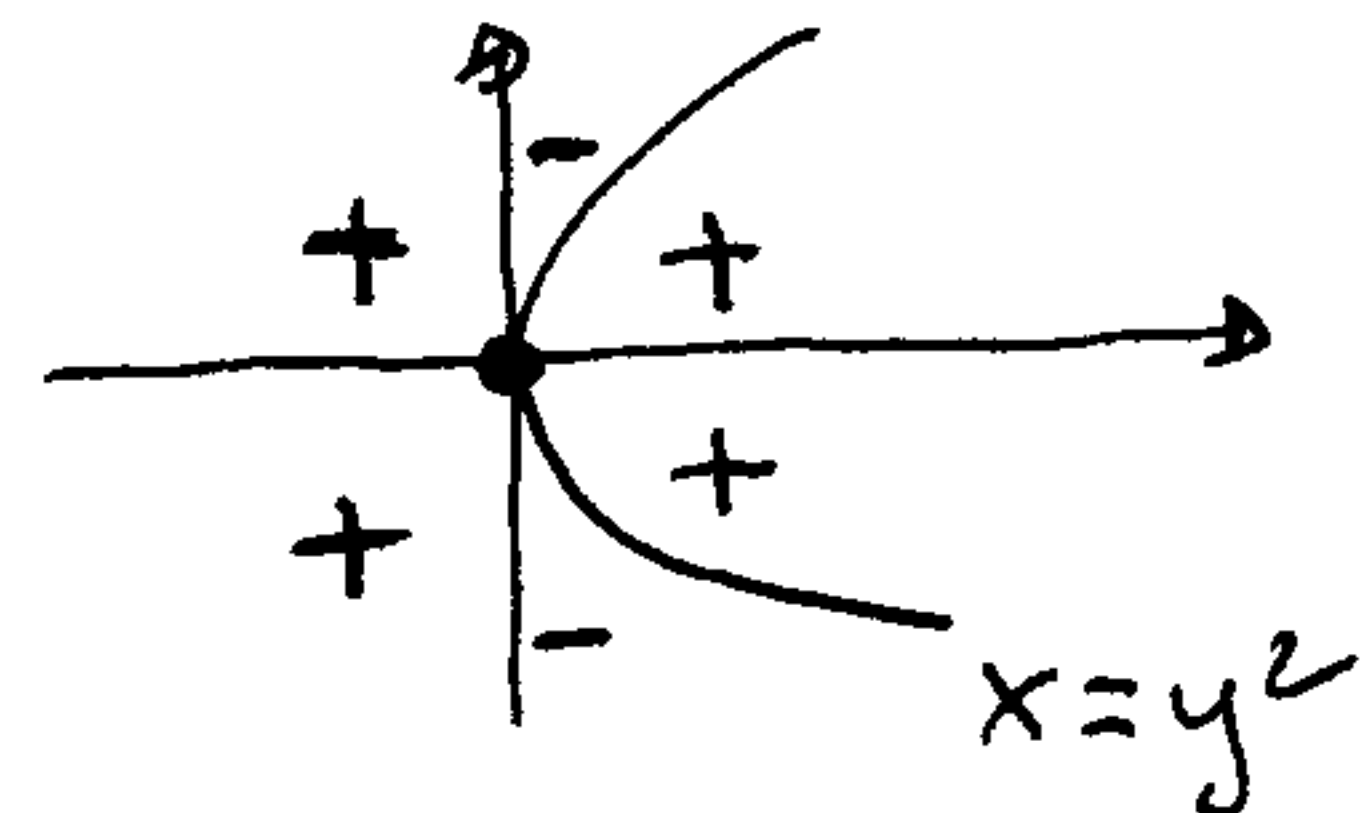
$$\nabla f(x;y) = (0;0) \Rightarrow \begin{cases} f'_x = 2x - y^2 + ky = 0 \\ f'_y = -2xy + kx = 0 \end{cases} \Rightarrow \begin{cases} x(k-2y) = 0 \\ 2x - y^2 + ky = 0 \end{cases} \Rightarrow \begin{cases} x=0 \\ y(k-y) = 0 \end{cases} \Rightarrow$$

$$\Rightarrow \begin{cases} x=0 \\ y=0 \end{cases} \cup \begin{cases} x=0 \\ y=k \end{cases} \cup \begin{cases} y = \frac{k}{2} \\ 2x - \frac{k^2}{4} + \frac{k^2}{2} = 2x + \frac{k^2}{4} = 0 \end{cases} \Rightarrow \begin{cases} y = \frac{k}{2} \\ x = -\frac{k^2}{8} \end{cases}.$$

We have three stationary points:  $P_1 = (0;0)$ ;  $P_2 = (0;k)$ ;  $P_3 = (-\frac{k^2}{8}; \frac{k}{2})$ .

$$H(x;y) = \begin{vmatrix} 2 & k-2y \\ k-2y & -2x \end{vmatrix}. \quad H(0;0) = \begin{vmatrix} 2 & k \\ k & 0 \end{vmatrix}. \quad \text{For } k \neq 0: |H_2| = -k^2 < 0: \text{Saddle point.}$$

For  $k=0$ :  $f(x;y) = x^2 - xy^2 = x \cdot (x - y^2)$ ;  $f(0;0) = 0$ ;  $f(x;y) \geq 0$ :

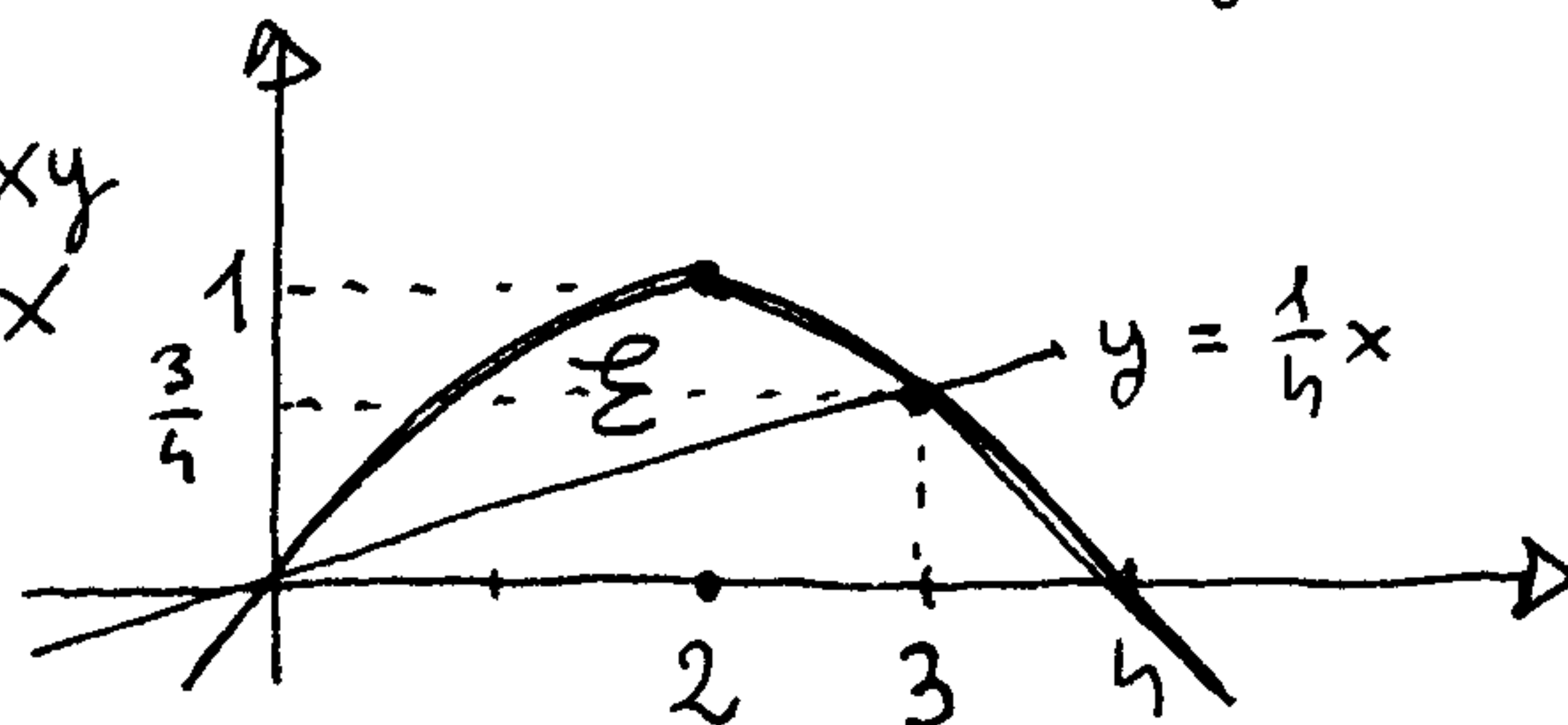


For  $k=0$   $P_1 = (0;0)$  is a Saddle point.

$$H(0;k) = \begin{vmatrix} 2 & -k \\ -k & 0 \end{vmatrix}. \quad \text{For } k \neq 0: |H_2| = -k^2 < 0: \text{Saddle Point. For } k=0: \text{already studied.}$$

$$H(-\frac{k^2}{8}; \frac{k}{2}) = \begin{vmatrix} 2 & 0 \\ 0 & \frac{k^2}{4} \end{vmatrix}. \quad \text{For } k \neq 0: \begin{cases} |H_1| > 0 \\ |H_2| > 0 \end{cases}: \text{Minimum Point. For } k=0: \text{already studied.}$$

PM 4)  $\begin{cases} \text{Max/min } f(x;y) = x \cdot y \\ \text{u.e. } \begin{cases} x^2 - 4x + 4y \leq 0 \\ x - 4y \leq 0 \end{cases} \end{cases} \Rightarrow \begin{cases} \text{Max/min } f(x;y) = xy \\ \text{u.e. } \begin{cases} y \leq -\frac{1}{4}x^2 + x \\ y \geq \frac{1}{4}x \end{cases} \end{cases}$



$\mathcal{E}$  is a bounded and closed set. The constraints are qualified.

$f(x,y)$  is a continuous function: there are maximum and minimum points from Weierstrass Theorem

$$\Lambda = xy - \lambda_1(x^2 - 4x + 4y) - \lambda_2(x - 4y).$$

If  $\lambda_1 = \lambda_2 = 0$

$$\begin{cases} \Lambda'_x = y = 0 \\ \Lambda'_y = x = 0 \\ x^2 - 4x + 4y \leq 0 \\ x - 4y \leq 0 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 0 \\ 0 \leq 0 \\ 0 \leq 0 \end{cases} \quad H(x,y) = H(0,0) = \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix}; |H_2| = -1 < 0: \text{Saddle point for free Max/min.}$$

If  $\lambda_1 \neq 0; \lambda_2 = 0$

$$\begin{cases} \Lambda'_x = y - 2\lambda_1 x + 4\lambda_1 = 0 \\ \Lambda'_y = x - 4\lambda_1 = 0 \\ \gamma = x - \frac{x^2}{4} \\ \gamma \geq \frac{1}{4}x \end{cases} \Rightarrow \begin{cases} x = 4\lambda_1 \\ y - 8\lambda_1^2 + 4\lambda_1 = 0 \\ \gamma = x - \frac{x^2}{4} \\ \gamma \geq \frac{1}{4}x \end{cases} \Rightarrow \begin{cases} x = 4\lambda_1 \\ y = 8\lambda_1^2 - 4\lambda_1 \\ 8\lambda_1^2 - 4\lambda_1 = 4\lambda_1 - 4\lambda_1^2 \Rightarrow \\ \gamma \geq \frac{1}{4}x \end{cases}$$

$$\Rightarrow 12\lambda_1^2 + 8\lambda_1 = 4\lambda_1(3\lambda_1 - 2) = 0 \Rightarrow \lambda_1 = 0 \text{ and } \lambda_1 = \frac{2}{3}.$$

$$\begin{cases} \lambda_1 = 0 \\ x = 0 \text{ already studied;} \\ \gamma = 0 \\ 0 \geq 0 \end{cases} \quad \begin{cases} \lambda_1 = \frac{2}{3} > 0 \\ x = \frac{8}{3} \\ \gamma = \frac{8}{3} - \frac{1}{4} \cdot \frac{64}{9} = \frac{96 - 64}{36} = \frac{32}{36} = \frac{8}{9} \\ \frac{8}{9} \geq \frac{1}{12} \text{ satisfied.} \end{cases} \Rightarrow \left(\frac{8}{3}; \frac{8}{9}\right) \text{ MAX??}$$

If  $\lambda_1 = 0; \lambda_2 \neq 0$

$$\begin{cases} \Lambda'_x = \gamma - \lambda_2 = 0 \\ \Lambda'_y = x + 4\lambda_2 = 0 \\ \gamma = \frac{1}{4}x \\ \gamma \leq x - \frac{x^2}{4} \end{cases} \Rightarrow \begin{cases} x = -4\lambda_2 \\ \gamma = \lambda_2 \\ \lambda_2 = \frac{1}{4} \cdot (-4\lambda_2) \\ \gamma \leq x - \frac{x^2}{4} \end{cases} \Rightarrow \begin{cases} 2\lambda_2 = 0 \Rightarrow \lambda_2 = 0 \\ x = 0 \\ \gamma = 0 \\ 0 \leq 0 \end{cases} \text{ already studied.}$$

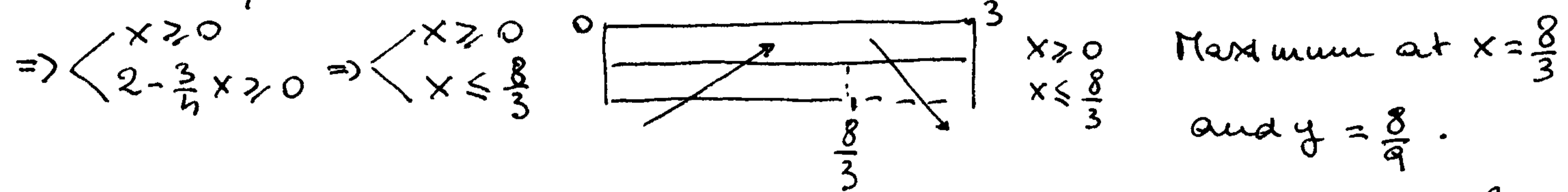
if  $\lambda_1 \neq 0; \lambda_2 \neq 0$

$$\begin{cases} \Lambda'_x = y - 2\lambda_1 x + 4\lambda_1 - \lambda_2 = 0 \\ \Lambda'_y = x - 4\lambda_1 + 4\lambda_2 = 0 \\ y = x - \frac{x^2}{4} \Rightarrow \begin{cases} \frac{1}{4}x = x - \frac{x^2}{4} \\ y = \frac{1}{4}x \end{cases} \Rightarrow \begin{cases} x^2 - 3x = 0 \\ y = \frac{1}{4}x \end{cases} \Rightarrow \begin{cases} x(x-3) = 0 \\ y = \frac{1}{4}x \end{cases} \Rightarrow \begin{cases} x=0 \\ y=0 \end{cases} \text{ and } \begin{cases} x=3 \\ y=\frac{3}{4} \end{cases} \end{cases}$$

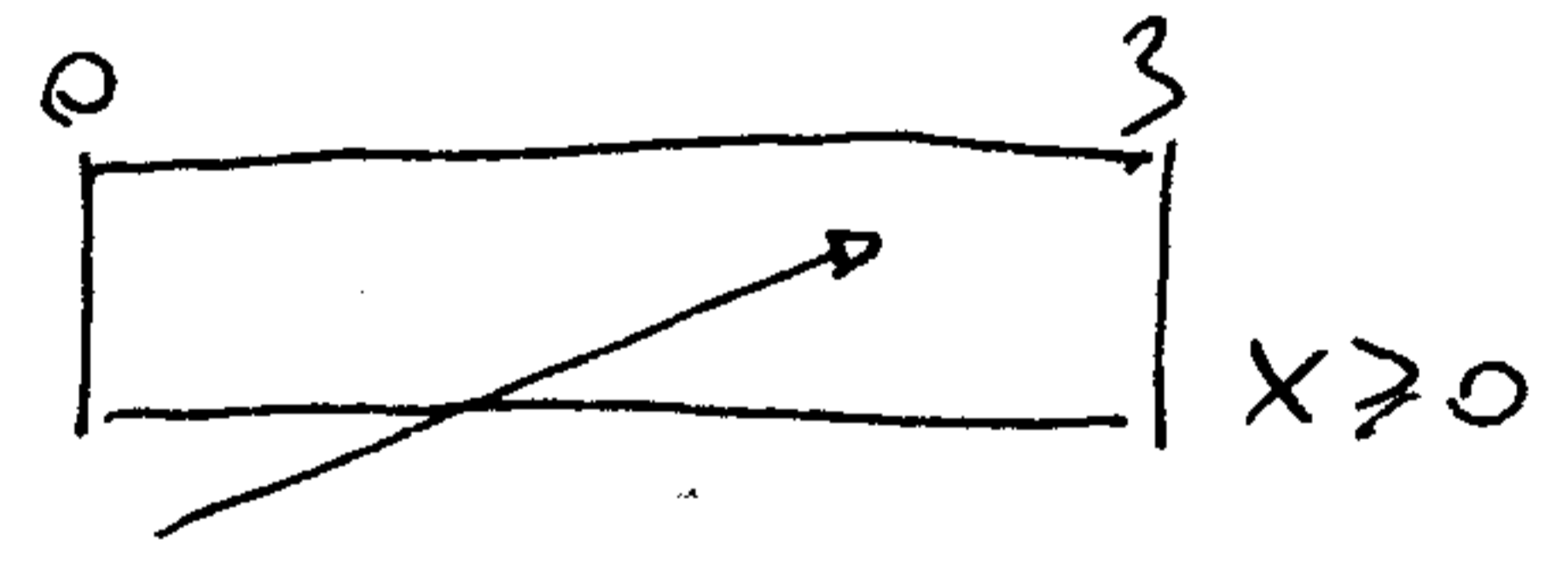
$$\begin{cases} x=0 \\ y=0 \\ 4\lambda_1 - \lambda_2 = 0 \\ -4\lambda_1 + 4\lambda_2 = 0 \end{cases} \Rightarrow \begin{cases} x=0 \\ y=0 \\ \lambda_1=0 \\ \lambda_2=0 \end{cases} \text{ already studied.}$$

$$\begin{cases} x=3 \\ y=\frac{3}{4} \\ \frac{3}{4} - 6\lambda_1 + 4\lambda_1 - \lambda_2 = 0 \\ 3 - 4\lambda_1 + 4\lambda_2 = 0 \end{cases} \Rightarrow \begin{cases} x=3 \\ y=\frac{3}{4} \\ 2\lambda_1 + \lambda_2 = \frac{3}{4} \\ 4\lambda_1 - 4\lambda_2 = 3 \end{cases} \Rightarrow \begin{cases} x=3 \\ y=\frac{3}{4} \\ \lambda_2 = \frac{3}{4} - 2\lambda_1 \\ 4\lambda_1 - 3 + 8\lambda_1 = 12\lambda_1 - 3 = 3 \end{cases} \Rightarrow \begin{cases} x=3 \\ y=\frac{3}{4} \\ \lambda_1 = \frac{1}{2} > 0 \\ \lambda_2 = -\frac{1}{4} < 0 \end{cases} \text{ Nothing}$$

For  $y = x - \frac{x^2}{4}$ :  $f(x) = x(x - \frac{x^2}{4}) = x^2 - \frac{x^3}{4}$ ;  $f'(x) = 2x - \frac{3}{4}x^2 = x(2 - \frac{3}{4}x) \geq 0 \Rightarrow$



For  $y = \frac{1}{4}x$ :  $f(x) = x \cdot \frac{1}{4}x = \frac{1}{4}x^2$ ;  $f'(x) = \frac{1}{2}x \geq 0 \Rightarrow x \geq 0$



$(\frac{8}{3}; \frac{8}{9})$  is the absolute maximum point with  $f(\frac{8}{3}; \frac{8}{9}) = \frac{64}{27}$ ;  
 $(0; 0)$  is not a Saddle point but it is the minimum point, with  $f(0; 0) = 0$ .

