

# QUANTITATIVE METHODS for ECONOMIC APPLICATIONS

## MATHEMATICS for ECONOMIC APPLICATIONS

### TASK 6/10/2020

IM 1) Calculate  $\sqrt{(1 + \sqrt{3}i)^3}$ .

Since  $1 + \sqrt{3}i = 2 \left( \frac{1}{2} + \frac{\sqrt{3}}{2}i \right) = 2 \left( \cos \frac{\pi}{3} + i \sin \frac{\pi}{3} \right)$  we get:

$$(1 + \sqrt{3}i)^3 = 8 \left( \cos 3 \frac{\pi}{3} + i \sin 3 \frac{\pi}{3} \right) = 8 (\cos \pi + i \sin \pi) = -8.$$

And finally:

$$\sqrt{(1 + \sqrt{3}i)^3} = \sqrt{-8} = \sqrt{8} \left[ \cos \left( \frac{\pi}{2} + k \frac{2\pi}{2} \right) + i \sin \left( \frac{\pi}{2} + k \frac{2\pi}{2} \right) \right], 0 \leq k \leq 1.$$

For  $k = 0$  we get  $z_0 = \sqrt{8} \left( \cos \frac{\pi}{2} + i \sin \frac{\pi}{2} \right) = 2\sqrt{2}i$ ;

for  $k = 1$  we get  $z_1 = \sqrt{8} \left( \cos \frac{3\pi}{2} + i \sin \frac{3\pi}{2} \right) = -2\sqrt{2}i$ .

IM 2) Given the linear map  $f : \mathbb{R}^4 \rightarrow \mathbb{R}^3$  having matrix  $\mathbb{A} = \begin{vmatrix} 1 & -1 & 2 & 1 \\ 0 & 2 & 1 & 2 \\ 2 & 0 & k & m \end{vmatrix}$ , determi-

ne the value of the parameters  $k$  and  $m$  if the Kernel and the Image have the same dimension. For such values find a basis for the Kernel of the linear map generated by  $\mathbb{A}$ .

To get  $\text{Dim}(\text{Imm}) = \text{Dim}(\text{Ker})$  we need  $\text{Rank}(\mathbb{A}) = 2$ .

By elementary operations on the rows ( $R_3 \leftarrow R_3 - 2R_1$ ) we get :

$$\begin{vmatrix} 1 & -1 & 2 & 1 \\ 0 & 2 & 1 & 2 \\ 2 & 0 & k & m \end{vmatrix} \rightarrow \begin{vmatrix} 1 & -1 & 2 & 1 \\ 0 & 2 & 1 & 2 \\ 0 & 2 & k-4 & m-2 \end{vmatrix};$$

By elementary operations on the rows ( $R_3 \leftarrow R_3 - R_2$ ) we get :

$$\begin{vmatrix} 1 & -1 & 2 & 1 \\ 0 & 2 & 1 & 2 \\ 0 & 2 & k-4 & m-2 \end{vmatrix} \rightarrow \begin{vmatrix} 1 & -1 & 2 & 1 \\ 0 & 2 & 1 & 2 \\ 0 & 0 & k-5 & m-4 \end{vmatrix}.$$

So  $\text{Dim}(\text{Imm}) = \text{Rank}(\mathbb{A}) = \text{Dim}(\text{Ker}) = 2$  for  $k = 5$  and  $m = 4$ .

And so  $\mathbb{A} = \begin{vmatrix} 1 & -1 & 2 & 1 \\ 0 & 2 & 1 & 2 \\ 2 & 0 & 5 & 4 \end{vmatrix}$ .

To find a basis for the Kernel of the linear map generated by  $\mathbb{A}$  we must firstly solve the sys-

tem:  $\mathbb{A} \cdot \mathbb{X} = \mathbb{O} \Rightarrow \begin{vmatrix} 1 & -1 & 2 & 1 \\ 0 & 2 & 1 & 2 \\ 2 & 0 & 5 & 4 \end{vmatrix} \cdot \begin{vmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{vmatrix} = \begin{vmatrix} 0 \\ 0 \\ 0 \end{vmatrix}.$

So we get the system: 
$$\begin{cases} x_1 - x_2 + 2x_3 + x_4 = 0 \\ 2x_2 + x_3 + 2x_4 = 0 \\ 2x_1 + 5x_3 + 4x_4 = 0 \end{cases}$$
 which however, for the elementary operations on the rows that we have already done, is equivalent to the system:

$$\begin{cases} x_1 - x_2 + 2x_3 + x_4 = 0 \\ 2x_2 + x_3 + 2x_4 = 0 \end{cases} \Rightarrow \begin{cases} x_4 = -x_1 + x_2 - 2x_3 \\ -2x_1 + 4x_2 - 3x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_3 = -\frac{2}{3}x_1 + \frac{4}{3}x_2 \\ x_4 = \frac{1}{3}x_1 - \frac{5}{3}x_2 \end{cases}.$$

Each vector of the Kernel can be represented as  $\mathbb{X} = \left( x_1, x_2, -\frac{2}{3}x_1 + \frac{4}{3}x_2, \frac{1}{3}x_1 - \frac{5}{3}x_2 \right)$ .

If we choose  $x_1 = 3$  and  $x_2 = 0$  we get the vector  $\mathbb{X}_1 = (3, 0, -2, 1)$ .

If we choose  $x_1 = 0$  and  $x_2 = 3$  we get the vector  $\mathbb{X}_2 = (0, 3, 4, -5)$ .

So a basis for the Kernel is:  $\mathbb{X} = \{(3, 0, -2, 1), (0, 3, 4, -5)\}$ .

I M 3) Given the matrix  $\mathbb{A} = \begin{vmatrix} 2 & 2 & -1 \\ 3 & 0 & -2 \\ k & 2 & 1 \end{vmatrix}$ , find the value of the parameter  $k$  knowing

that the matrix admits the eigenvalue  $\lambda = -1$  and then determine, for this value of the parameter, if the matrix is diagonalizable or not.

From  $|\mathbb{A} - \lambda \mathbb{I}| = 0$  we get:

$$\begin{vmatrix} 2-\lambda & 2 & -1 \\ 3 & -\lambda & -2 \\ k & 2 & 1-\lambda \end{vmatrix} = \begin{vmatrix} 2-\lambda-k & 0 & \lambda-2 \\ 3 & -\lambda & -2 \\ k & 2 & 1-\lambda \end{vmatrix} =$$

$$= (2-\lambda-k)(\lambda^2 - \lambda + 4) + (\lambda-2)(6+k\lambda) = 0.$$

If  $\lambda = -1$  we get  $(3-k)(6) + (-3)(6-k) = 18 - 6k - 18 + 3k = 0 \Rightarrow k = 0$ .

So  $\mathbb{A} = \begin{vmatrix} 2 & 2 & -1 \\ 3 & 0 & -2 \\ 0 & 2 & 1 \end{vmatrix}$ . And also:

$$|\mathbb{A} - \lambda \mathbb{I}| = (2-\lambda)(\lambda^2 - \lambda + 4) + (\lambda-2)(6) = (2-\lambda)(\lambda^2 - \lambda - 2) = 0 \Rightarrow$$

$$\Rightarrow (2-\lambda)(\lambda-2)(\lambda+1) = 0 \Rightarrow \lambda_1 = \lambda_2 = 2, \lambda_3 = -1.$$

To check if the matrix is diagonalizable or not we have to find the Rank of  $\|\mathbb{A} - 2\mathbb{I}\|$ :

$$\|\mathbb{A} - 2\mathbb{I}\| = \begin{vmatrix} 0 & 2 & -1 \\ 3 & -2 & -2 \\ 0 & 2 & -1 \end{vmatrix}. \text{ Since } \begin{vmatrix} 0 & 2 \\ 3 & -2 \end{vmatrix} = -6 \neq 0 \text{ it is } \text{Rank}(\mathbb{A} - 2\mathbb{I}) = 2 \text{ for}$$

which it is  $m_2^g = 3 - 2 = 1 < m_2^a = 2$  and so the matrix is not a diagonalizable one.

I M 4) Find the coordinates of the vector  $\mathbb{X}$  in the basis  $\mathbb{V} = \{(1, 0, 0), (1, 1, 0), (1, 0, 1)\}$  if it has coordinates  $(2, 0, -1)$  in the basis  $\mathbb{W} = \{(1, 1, 0), (1, -1, 1), (1, 0, 1)\}$ .

Since  $\mathbb{X}$  has coordinates  $(2, 0, -1)$  in the basis  $\mathbb{W} = \{(1, 1, 0), (1, -1, 1), (1, 0, 1)\}$ , it is:

$$\mathbb{X} = \begin{vmatrix} 1 & 1 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & 1 \end{vmatrix} \cdot \begin{vmatrix} 2 \\ 0 \\ -1 \end{vmatrix} = \begin{vmatrix} 1 \\ 2 \\ -1 \end{vmatrix}.$$

To find the coordinates of the vector  $\mathbb{X}$  in the basis  $\mathbb{V} = \{(1, 0, 0), (1, 1, 0), (1, 0, 1)\}$  we have to solve the system:

$$\begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} \cdot \begin{vmatrix} x \\ y \\ z \end{vmatrix} = \begin{vmatrix} 1 \\ 2 \\ -1 \end{vmatrix} \Rightarrow \begin{cases} x + y + z = 1 \\ y = 2 \\ z = -1 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 2 \\ z = -1 \end{cases}.$$

II M 1) Solve the problem : 
$$\begin{cases} \text{Max/min } f(x, y) = x^2 - y^2 \\ \text{u.c. : } x^2 \leq y \leq 1 \end{cases} .$$

The objective function of the problem is a continuous function, the constraints define a feasible region which is a compact and bounded set, and so we can apply Weierstrass Theorem.

Surely the function admits maximum value and minimum value.

To solve the problem we use the Kuhn-Tucker conditions.

We write the problem as 
$$\begin{cases} \text{Max/min } f(x, y) = x^2 - y^2 \\ \text{u.c.: } \begin{cases} x^2 - y \leq 0 \\ y - 1 \leq 0 \end{cases} \end{cases}$$

$$\Lambda(x, y, \lambda_1, \lambda_2) = x^2 - y^2 - \lambda_1(x^2 - y) - \lambda_2(y - 1) .$$

By applying the first order conditions we have:

1) case  $\lambda_1 = 0, \lambda_2 = 0$  :

$$\begin{cases} \Lambda'_x = 2x = 0 \\ \Lambda'_y = -2y = 0 \\ x^2 - y \leq 0 \\ y - 1 \leq 0 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 0 \\ 0 \leq 0 \\ -1 \leq 0 \end{cases} . \text{ Since } \mathbb{H}(x, y) = \begin{vmatrix} 2 & 0 \\ 0 & -2 \end{vmatrix} = \mathbb{H}(0, 0) \text{ we have that,}$$

globally, the point  $(0, 0)$  is a saddle point. We will study it more precisely later.

2) case  $\lambda_1 \neq 0, \lambda_2 = 0$  :

$$\begin{cases} \Lambda'_x = 2x - 2\lambda_1 x = 2x(1 - \lambda_1) = 0 \\ \Lambda'_y = -2y + \lambda_1 = 0 \\ y = x^2 \\ y \leq 1 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 0 \\ \lambda_1 = 0 \\ 0 \leq 1 \end{cases} : \text{ we will study it more precisely later;}$$

$$\begin{cases} \Lambda'_x = 2x - 2\lambda_1 x = 2x(1 - \lambda_1) = 0 \\ \Lambda'_y = -2y + \lambda_1 = 0 \\ y = x^2 \\ y \leq 1 \end{cases} \Rightarrow \begin{cases} x^2 = \frac{1}{2} \\ y = \frac{1}{2} \\ \lambda_1 = 1 \\ \frac{1}{2} \leq 1 \end{cases} \Rightarrow \begin{cases} x = \frac{1}{\sqrt{2}} \\ y = \frac{1}{2} \\ \lambda_1 = 1 \\ \frac{1}{2} \leq 1 \end{cases} \cup \begin{cases} x = -\frac{1}{\sqrt{2}} \\ y = \frac{1}{2} \\ \lambda_1 = 1 \\ \frac{1}{2} \leq 1 \end{cases} .$$

Since  $\lambda_1 > 0$  the points  $\left(\frac{1}{\sqrt{2}}, \frac{1}{2}\right)$  and  $\left(-\frac{1}{\sqrt{2}}, \frac{1}{2}\right)$  may be maximum points.

3) case  $\lambda_1 = 0, \lambda_2 \neq 0$  :

$$\begin{cases} \Lambda'_x = 2x = 0 \\ \Lambda'_y = -2y - \lambda_2 = 0 \\ y = 1 \\ x^2 \leq y \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 1 \\ \lambda_2 = -2 < 0 \\ 0 \leq 1 \end{cases} .$$

Since  $\lambda_2 < 0$  the point  $(0, 1)$  may be a minimum point.

4) case  $\lambda_1 \neq 0, \lambda_2 \neq 0$  :

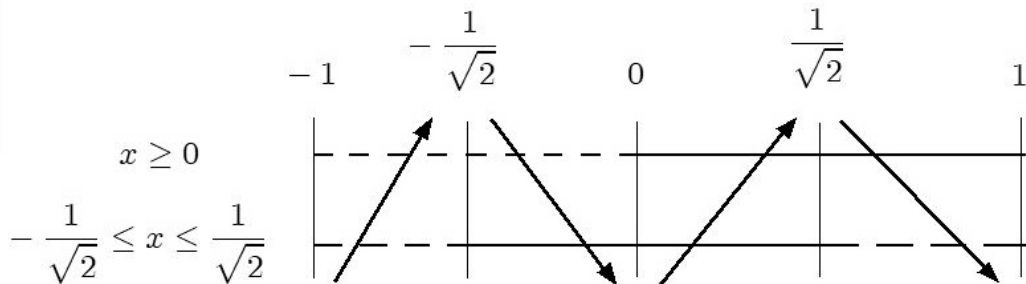
$$\begin{cases} \Lambda'_x = 2x - 2\lambda_1 x = 0 \\ \Lambda'_y = -2y + \lambda_1 - \lambda_2 = 0 \\ y = x^2 \\ y = 1 \end{cases} \Rightarrow \begin{cases} x = 1 \\ y = 1 \\ 2 - 2\lambda_1 = 0 \\ \lambda_1 - \lambda_2 = 2 \end{cases} \cup \begin{cases} x = -1 \\ y = 1 \\ -2 + 2\lambda_1 = 0 \\ \lambda_1 - \lambda_2 = 2 \end{cases} \Rightarrow$$

$\Rightarrow \begin{cases} x = 1 \\ y = 1 \\ \lambda_1 = 1 \\ \lambda_2 = -1 \end{cases} \cup \begin{cases} x = -1 \\ y = 1 \\ \lambda_1 = 1 \\ \lambda_2 = -1 \end{cases}$ . The points  $(1, 1)$  and  $(-1, 1)$  are neither maximum nor minimum points.

Let's study the objective function on the constraint  $y = x^2$ .

It is  $f(x, x^2) = x^2 - x^4 \Rightarrow f'(x) = 2x - 4x^3 = 2x(1 - 2x^2) \geq 0$ .

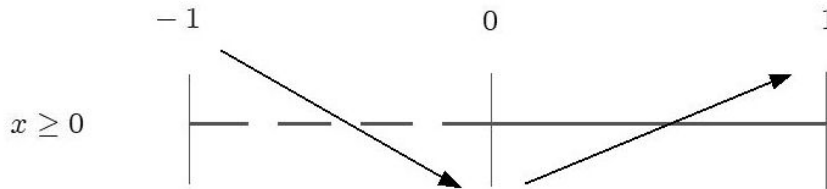
It is  $1 - 2x^2 \geq 0 \Rightarrow x^2 \leq \frac{1}{2} \Rightarrow -\frac{1}{\sqrt{2}} \leq x \leq \frac{1}{\sqrt{2}}$  and so:



The points  $\left(\frac{1}{\sqrt{2}}, \frac{1}{2}\right)$  and  $\left(-\frac{1}{\sqrt{2}}, \frac{1}{2}\right)$  are maximum points with  $f\left(\pm\frac{1}{\sqrt{2}}, \frac{1}{2}\right) = \frac{1}{4}$ .

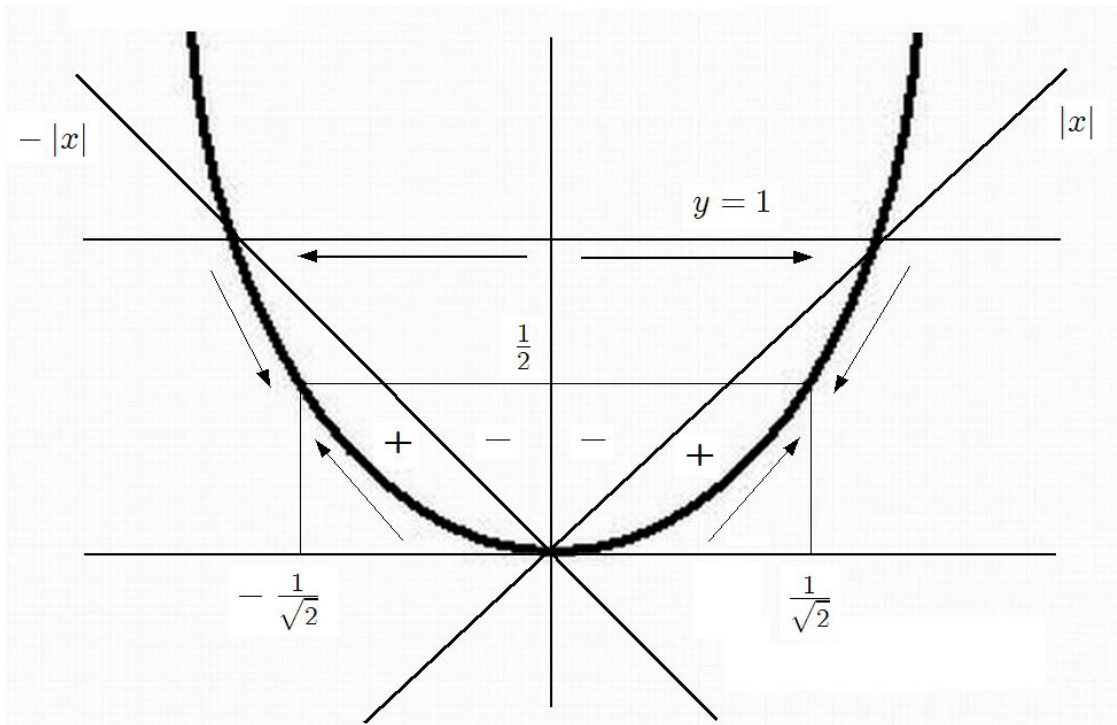
Let's study the objective function on the constraint  $y = 1$ .

It is  $f(x, 1) = x^2 - 1 \Rightarrow f'(x) = 2x \geq 0$  for  $x \geq 0$ .



The point  $(0, 1)$  is a minimum point with  $f(0, 1) = -1$ .

Finally we study the point  $(0, 0)$ . It is  $f(0, 0) = 0$ . Then  $f(x, y) = x^2 - y^2 \geq 0$  for  $y^2 \leq x^2$  satisfied for  $-|x| \leq y \leq |x|$ . In each neighborhood of the point  $(0, 0)$  we have both positive and negative values and therefore  $(0, 0)$  is a saddle point.



II M 2) Given the function  $f(x, y, z) = x^2 - xy + y^2 + z^2$  determine the nature of its stationary point.

We determine the stationary points of the function. Applying the first order conditions we have:

$$\nabla f(x, y, z) = \mathbf{0} \Rightarrow \begin{cases} f'_x = 2x - y = 0 \\ f'_y = -x + 2y = 0 \\ f'_z = 2z = 0 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 0 \\ z = 0 \end{cases} .$$

Then we apply the second order conditions:  $\mathbb{H}(x, y, z) = \begin{vmatrix} 2 & -1 & 0 \\ -1 & 2 & 0 \\ 0 & 0 & 2 \end{vmatrix} = \mathbb{H}(0, 0, 0)$ .

Since:  $\begin{cases} |\mathbb{H}_1| = 2 > 0 \\ |\mathbb{H}_2| = 3 > 0 \\ |\mathbb{H}_3| = 6 > 0 \end{cases}$  the point  $(0, 0, 0)$  is a minimum point.

II M 3) Given the function  $f(x, y) = e^{x^2+y^2}$  and the unit vector  $v = (\cos \alpha, \sin \alpha)$  calculate its directional derivatives  $\mathcal{D}_{v,v}^2 f(0, 0)$ .

The function  $f(x, y) = e^{x^2+y^2}$  it is clearly differentiable of every order  $\forall (x, y) \in \mathbb{R}^2$ . So  $\mathcal{D}_{v,v}^2 f(0, 0) = v \cdot \mathbb{H}f(0, 0) \cdot v^T$ .

From  $\nabla f(x, y) = (2x e^{x^2+y^2}; 2y e^{x^2+y^2})$  we get :

$$\mathbb{H}(x, y) = \begin{vmatrix} 2(1 + 2x^2) e^{x^2+y^2} & 4xy e^{x^2+y^2} \\ 4xy e^{x^2+y^2} & 2(1 + 2y^2) e^{x^2+y^2} \end{vmatrix} \Rightarrow \mathbb{H}(0, 0) = \begin{vmatrix} 2 & 0 \\ 0 & 2 \end{vmatrix} \text{ and so:}$$

$$\mathcal{D}_{v,v}^2 f(0, 0) = \begin{vmatrix} \cos \alpha & \sin \alpha \end{vmatrix} \cdot \begin{vmatrix} 2 & 0 \\ 0 & 2 \end{vmatrix} \cdot \begin{vmatrix} \cos \alpha \\ \sin \alpha \end{vmatrix} = 2 \cos^2 \alpha + 2 \sin^2 \alpha = 2 .$$

II M 4) Given the equation  $f(x, y) = x \sin y - y \cos x = 0$ , verify if at  $P_0 = (0, 0)$  it is possible to define an implicit function having  $y$  as dependent variable of  $x$  and then calculate the partial derivative of the first order of  $y(x)$  at  $x = 0$ .

The function  $f(x, y)$  is a differentiable function  $\forall (x, y) \in \mathbb{R}^2$ ,  $f(0, 0) = 0 - 0 = 0$ .

It is then:  $\nabla f(x, y) = (\sin y + y \sin x; x \cos y - \cos x)$ .

So  $\nabla f(0, 0) = (0; -1)$ . Since  $f'_y(0, 0) = -1 \neq 0$  we can define an implicit function  $x \rightarrow y(x)$  whose first order derivative is:

$$\frac{dy}{dx}(0) = -\frac{f'_x(0, 0)}{f'_y(0, 0)} = -\frac{0}{-1} = 0.$$