

**QUANTITATIVE METHODS for ECONOMIC APPLICATIONS**  
**MATHEMATICS for ECONOMIC APPLICATIONS**  
**TASK 1/9/2021**

I M 1) Calculate the square roots of the number  $z = \frac{1}{1+i}$ .

Since  $1+i = \sqrt{2} \left( \frac{1}{\sqrt{2}} + i \frac{1}{\sqrt{2}} \right) = \sqrt{2} \left( \cos \frac{\pi}{4} + i \sin \frac{\pi}{4} \right)$  we get:

$$z = \frac{1}{1+i} = \frac{1}{\sqrt{2}} \left( \cos \left( -\frac{\pi}{4} \right) + i \sin \left( -\frac{\pi}{4} \right) \right) = \frac{1}{\sqrt{2}} \left( \cos \frac{7\pi}{4} + i \sin \frac{7\pi}{4} \right).$$

Or even  $z = \frac{1}{1+i} = \frac{1-i}{(1+i)(1-i)} = \frac{\sqrt{2}}{2} \left( \cos \frac{7\pi}{4} + i \sin \frac{7\pi}{4} \right)$ . Then:

$$\sqrt{z} = \frac{1}{\sqrt[4]{2}} \left( \cos \left( \frac{7\pi}{8} + k\pi \right) + i \sin \left( \frac{7\pi}{8} + k\pi \right) \right); 0 \leq k \leq 1.$$

$$\text{For } k=0 : z_0 = \frac{1}{\sqrt[4]{2}} \left( \cos \frac{7\pi}{8} + i \sin \frac{7\pi}{8} \right);$$

$$\text{for } k=1 : z_1 = \frac{1}{\sqrt[4]{2}} \left( \cos \frac{15\pi}{8} + i \sin \frac{15\pi}{8} \right).$$

I M 2) Given the two orthogonal vectors  $\mathbb{X}_1 = (1, 1, -2)$  and  $\mathbb{X}_2 = (1, 1, 1)$ , determine a third vector  $\mathbb{X}_3$  orthogonal to both them and, with their unit vectors, form an orthogonal matrix. Finally, determine the inverse of this orthogonal matrix.

Firstly we determine a vector orthogonal to  $\mathbb{X}_2 = (1, 1, 1) : (x, y, z)$ .

It will be:  $(1, 1, 1) \cdot (x, y, z) = x + y + z = 0 \Rightarrow z = -x - y$ .

Now we determine a vector orthogonal to  $\mathbb{X}_1 = (1, 1, -2) : (x, y, -x - y)$ .

It will be:  $(1, 1, -2) \cdot (x, y, -x - y) = x + y + 2x + 2y = 3x + 3y = 0 \Rightarrow y = -x$ .

Therefore a vector orthogonal to both will be  $\mathbb{X}_3 = (x, -x, 0)$ .

By choosing  $x = 1$  we get  $\mathbb{X}_3 = (1, -1, 0)$ . Their unit vectors will be :

$$\overline{\mathbb{X}}_1 = \left( \frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}}, -\frac{2}{\sqrt{6}} \right), \overline{\mathbb{X}}_2 = \left( \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right), \overline{\mathbb{X}}_3 = \left( \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, 0 \right).$$

possible orthogonal matrix will be 
$$\mathbb{U} = \begin{vmatrix} \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} \\ -\frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} & 0 \end{vmatrix}.$$

Since the matrix is an orthogonal one, to get its inverse it is enough to make its transpose and

so we get 
$$\mathbb{U}^{-1} = \mathbb{U}^T = \begin{vmatrix} \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} & -\frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \end{vmatrix}.$$

I M 3) Given the matrix  $\mathbb{A} = \begin{vmatrix} k & 0 & k \\ 0 & -1 & 0 \\ k & 0 & k \end{vmatrix}$ , determine the values of  $k$  for which the matrix admits a multiple eigenvalue.

From  $|\mathbb{A} - \lambda \mathbb{I}| = \begin{vmatrix} k - \lambda & 0 & k \\ 0 & -1 - \lambda & 0 \\ k & 0 & k - \lambda \end{vmatrix} = \begin{vmatrix} -\lambda & 0 & k \\ 0 & -1 - \lambda & 0 \\ \lambda & 0 & k - \lambda \end{vmatrix} =$   
 $= -\lambda(-1 - \lambda)(k - \lambda) + \lambda(-k(-1 - \lambda)) = -\lambda(-1 - \lambda)((k - \lambda) + k) =$   
 $= \lambda(1 + \lambda)(2k - \lambda) = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = -1, \lambda_3 = 2k$ . Hence the matrix admits multiple eigenvalues if  $2k = 0 \Rightarrow k = 0$  or if  $2k = -1 \Rightarrow k = -\frac{1}{2}$ .

I M 4) Given the matrix  $\mathbb{A} = \begin{vmatrix} 1 & m & -1 & 1 \\ 2 & 1 & 1 & 2 \\ 1 & -1 & -4 & 1 \end{vmatrix}$  and the vector  $\mathbb{Y} = (2, 6, m)$ , determine for which value of  $m$  the vector  $\mathbb{Y}$  belongs to the Image of the linear map generated by  $\mathbb{A}$ .

To see if the vector  $\mathbb{Y}$  belongs to the Image of the linear map generated by the matrix  $\mathbb{A}$  it is sufficient to check that the linear system having for matrix  $\mathbb{A}$  and for vector of the known terms  $\mathbb{Y}$  is a system that admits solutions. So we have to apply the Rouché-Capelli Theorem.

$(\mathbb{A}|\mathbb{Y}) = \left\| \begin{array}{cccc|c} 1 & m & -1 & 1 & 2 \\ 2 & 1 & 1 & 2 & 6 \\ 1 & -1 & -4 & 1 & m \end{array} \right\|$ . By elementary operations on the rows:

$(R_2 \leftarrow R_2 - 2R_1), (R_3 \leftarrow R_3 - R_1)$ , and then  $(R_3 \leftarrow R_3 + R_2)$  we get:

$(\mathbb{A}|\mathbb{Y}) \rightarrow \left\| \begin{array}{cccc|c} 1 & m & -1 & 1 & 2 \\ 0 & 1 - 2m & 3 & 0 & 2 \\ 0 & -1 - m & -3 & 0 & m - 2 \end{array} \right\| \rightarrow \left\| \begin{array}{cccc|c} 1 & m & -1 & 1 & 2 \\ 0 & 1 - 2m & 3 & 0 & 2 \\ 0 & -3m & 0 & 0 & m \end{array} \right\|$ .

And so, if  $m = 0$  we get  $\text{Rank}(\mathbb{A}) = 2 = \text{Rank}(\mathbb{A}|\mathbb{Y})$ : the system has  $\infty^2$  solutions and the vector  $\mathbb{Y}$  belongs to the Image of the linear map;

If  $m \neq 0$  we get  $\text{Rank}(\mathbb{A}) = 3 = \text{Rank}(\mathbb{A}|\mathbb{Y})$ : the system has  $\infty^1$  solutions and the vector  $\mathbb{Y}$  belongs to the Image of the linear map.

In conclusion, the vector  $\mathbb{Y}$  belongs to the Image for each value of  $m$ .

II M 1) Given  $f(x, y) = x e^y$  and  $P_0 = (1, 0)$ , find all the directions  $v = (\cos \alpha, \sin \alpha)$  for which it is:  $\mathcal{D}_v f(P_0) = 0$ .

The function  $f(x, y) = x e^y$  is differentiable and so  $\mathcal{D}_v f(P_0) = \nabla f(P_0) \cdot v$ .

From  $\nabla f(x, y) = (e^y, x e^y)$  we get  $\nabla f(1, 0) = (1, 1)$ . Finally:

$\mathcal{D}_v f(1, 0) = (1, 1) \cdot (\cos \alpha, \sin \alpha) = \cos \alpha + \sin \alpha = 0 \Rightarrow \cos \alpha = -\sin \alpha$  and so:

$\alpha = \frac{3\pi}{4}$  or  $\alpha = \frac{7\pi}{4}$ .

II M 2) Solve the problem  $\begin{cases} \text{Max/min } f(x, y) = 2x - 3y \\ \text{u.c. : } x^2 + y^2 \leq 4 \end{cases}$ .

The objective function of the problem is a continuous function, the constraint defines a feasible region, a circumference, which is a closed and bounded (compact) set, and so we can apply Weierstrass Theorem. Surely the function admits maximum value and minimum value.

To solve the problem we use the Kuhn-Tucker conditions.

We write the problem as 
$$\begin{cases} \text{Max/min } f(x, y) = 2x - 3y \\ \text{u.c. : } x^2 + y^2 - 4 \leq 0 \end{cases}.$$

We form the Lagrangian function:

$$\Lambda(x, y, \lambda) = 2x - 3y - \lambda(x^2 + y^2 - 4).$$

By applying the first order conditions we have:

1) case  $\lambda = 0$  :

$$\begin{cases} \Lambda'_x = 2 \neq 0 \\ \Lambda'_y = -3 \neq 0 \\ x^2 + y^2 \leq 4 \end{cases} \Rightarrow \text{no solution.}$$

2) case  $\lambda \neq 0$  :

$$\begin{aligned} \begin{cases} \Lambda'_x = 2 - 2\lambda x = 2(1 - \lambda x) = 0 \\ \Lambda'_y = -3 - 2\lambda y = 0 \\ x^2 + y^2 = 4 \end{cases} &\Rightarrow \begin{cases} x = \frac{1}{\lambda} \\ y = -\frac{3}{2\lambda} \\ \frac{1}{\lambda^2} + \frac{9}{4\lambda^2} = 4 \end{cases} \Rightarrow \begin{cases} x = \frac{1}{\lambda} \\ y = -\frac{3}{2\lambda} \\ \frac{1}{\lambda^2} \left(1 + \frac{9}{4}\right) = 4 \end{cases} \Rightarrow \\ \Rightarrow \begin{cases} x = \frac{1}{\lambda} \\ y = -\frac{3}{2\lambda} \\ \lambda^2 = \frac{13}{16} \end{cases} &\Rightarrow \begin{cases} x = \frac{4}{\sqrt{13}} \\ y = -\frac{6}{\sqrt{13}} \\ \lambda = \frac{\sqrt{13}}{4} > 0 \end{cases} \cup \begin{cases} x = -\frac{4}{\sqrt{13}} \\ y = \frac{6}{\sqrt{13}} \\ \lambda = -\frac{\sqrt{13}}{4} < 0 \end{cases}. \end{aligned}$$

Since we have only two solutions, the point  $\left(\frac{4}{\sqrt{13}}, -\frac{6}{\sqrt{13}}\right)$  with  $\lambda > 0$  is the maximum point, with  $f\left(\frac{4}{\sqrt{13}}, -\frac{6}{\sqrt{13}}\right) = 2\sqrt{13}$  while  $\left(-\frac{4}{\sqrt{13}}, \frac{6}{\sqrt{13}}\right)$  with  $\lambda < 0$  is the minimum point with  $f\left(-\frac{4}{\sqrt{13}}, \frac{6}{\sqrt{13}}\right) = -2\sqrt{13}$ .

II M 3) Given the function  $f(x, y, z) = x e^{y-z} + x \log(2y - x)$ , calculate its gradient at the point  $P_0 = (1, 1, 1)$ .

Since:

$$\frac{\partial f}{\partial x} = e^{y-z} + \log(2y - x) + x \frac{1}{2y - x}(-1) = e^{y-z} + \log(2y - x) + \frac{x}{x - 2y};$$

$$\frac{\partial f}{\partial y} = x e^{y-z} + x \frac{1}{2y - x} 2 = x e^{y-z} + \frac{2x}{2y - x};$$

$$\frac{\partial f}{\partial z} = x e^{y-z}(-1) = -x e^{y-z}$$

it is  $\nabla f(1, 1, 1) = (1 + 0 - 1, 1 + 2, -1) = (0, 3, -1)$ .

II M 4) Given the equation  $f(x, y) = x^3 - 2y^3 - 3x + 4y = 0$ , satisfied at the point  $(1, 1)$ , verify that the hypotheses of Dini's theorem for defining an implicit function  $x \rightarrow y(x)$  are satisfied and then calculate  $y'(1)$ .

It is  $f(1, 1) = 1 - 2 - 3 + 4 = 0$  and so the equation is satisfied at  $(1, 1)$ .

The function  $f(x, y)$  is differentiable  $\forall (x, y) \in \mathbb{R}^2$ . And so:

$$\nabla f(x, y) = (3x^2 - 3, -6y^2 + 4) \Rightarrow \nabla f(1, 1) = (0, -2).$$

Since  $f'_y = -2 \neq 0$  the hypotheses of Dini's theorem are satisfied and we get:

$$y'(1) = -\frac{f'_x(1, 1)}{f'_y(1, 1)} = -\frac{0}{-2} = 0.$$