

UNIVERSITÀ DEGLI STUDI DI SIENA
Scuola di Economia e Management
A.A. 2024/25

Quantitative Methods for Economic Applications -
Mathematics for Economic Applications
Task 6/6/2025

I M 1) Find the complex number z such that it's satisfied the following equality:

$$\frac{(2-i)^2 - (2+i)^2}{z-2i} + 2i = 0.$$

$$\frac{(2-i)^2 - (2+i)^2}{z-2i} + 2i = \frac{(2-i)^2 - (2+i)^2 + 2i(z-2i)}{z-2i} =$$

$$\frac{4-4i+i^2 - (4+4i+i^2) + 2iz - 4i^2}{z-2i} = \frac{-8i + 2iz + 4}{z-2i}; \text{ put } -8i + 2iz + 4 = 0$$

$$\text{we find } z = \frac{8i-4}{2i} = \frac{4i-2}{i} = \frac{4i-2}{i} \cdot \frac{i}{i} = \frac{4i^2-2i}{i^2} = \frac{-4-2i}{-1} = 4+2i.$$

I M 2) Given the matrix $\mathbb{A} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 2 & 0 & 1 \end{bmatrix}$. Study if the matrix is diagonalizable and

for eigenvalue $\lambda = -2$ calculate a basis for the associated eigenspace.

To study the diagonalizability of \mathbb{A} we start with the calculus of the characteristic

polynomial of the matrix; $P_{\mathbb{A}}(\lambda) = |\lambda\mathbb{I} - \mathbb{A}| = \begin{vmatrix} \lambda-1 & 0 & 0 \\ 0 & \lambda+2 & 0 \\ -2 & 0 & \lambda-1 \end{vmatrix} =$

$(\lambda-1)^2(\lambda+2)$. Putting $P_{\mathbb{A}}(\lambda) = 0$ we find the three eigenvalues of matrix \mathbb{A} :

$\lambda_{1,2} = 1$, $\lambda_3 = -2$, the eigenvalue 1 has algebraic multiplicity equal two. To verify if the matrix is diagonalizable, we must find the geometric multiplicity of eigenvalue 1,

for our goal we calculate the rank of matrix $\mathbb{I} - \mathbb{A} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 & 0 \\ -2 & 0 & 0 \end{bmatrix}$, it's easy note that

from matrix \mathbb{A} we can define a principal minor of order 2, $\begin{bmatrix} 0 & 3 \\ -2 & 0 \end{bmatrix}$ with determinant

different from 0 and matrix $\mathbb{I} - \mathbb{A}$ has the first row null, thus $Rank(\mathbb{I} - \mathbb{A}) = 2$ and the geometric multiplicity of eigenvalue 1 is one. The matrix isn't diagonalizable. For a basis for the eigenspace associated at the eigenvalue $\lambda = -2$ we consider the matrix

$$-2\mathbb{I} - \mathbb{A} = \begin{bmatrix} -3 & 0 & 0 \\ 0 & 0 & 0 \\ -2 & 0 & -3 \end{bmatrix}; \text{ a generic vector that belongs to this eigenspace is a}$$

$$\text{vector } (x, y, z) \text{ such that } \begin{bmatrix} -3 & 0 & 0 \\ 0 & 0 & 0 \\ -2 & 0 & -3 \end{bmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -3z \\ 0 \\ -2x-3z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow$$

$x = z = 0$. Thus a generic vector that belongs to the eigenspace is a vector

$(0, y, 0) = y(0, 1, 0)$, and a basis for the eigenspace is the set $\mathcal{B}_{ES_{\lambda=-2}} = \{(0, 1, 0)\}$.

I M 3) Given a linear map $F: \mathbb{R}^3 \rightarrow \mathbb{R}^4$, with

$F(x_1, x_2, x_3) = (x_1 + x_2, x_2 + x_3, x_1 + x_2 + x_3, -x_1 - x_2 - x_3)$. Find the matrix

associated with the linear map, calculate the dimensions of both, kernel and image of F , and find a basis for the image.

A generic element of the image of linear map is the vector:

$$\begin{pmatrix} x_1 + x_2 \\ x_2 + x_3 \\ x_1 + x_2 + x_3 \\ -x_1 - x_2 - x_3 \end{pmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \\ -1 & -1 & -1 \end{bmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \text{ and easily we get that the}$$

matrix associated with the linear map is $\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \\ -1 & -1 & -1 \end{bmatrix}$. Now we reduce the

matrix by elementary operations on its lines:

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \\ -1 & -1 & -1 \end{bmatrix} \xrightarrow[R_4 \mapsto R_4 + R_3]{R_3 \mapsto R_3 - R_1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}; \text{ the matrix shows full rank, thus the}$$

dimension of the image is 3 and by the Rank-Nullity Theorem

$\dim(\text{Ker}(F)) = \dim(\mathbb{R}^3) - \dim(\text{Ima}(F)) = 3 - 3 = 0$. For a basis of the image note that a generic vector that belongs in the image

$(x_1 + x_2, x_2 + x_3, x_1 + x_2 + x_3, -x_1 - x_2 - x_3)$ has the fourth component equal the opposite of the third component and we can conclude that all the vectors in the image have form $(y_1, y_2, y_3, -y_3) = y_1(1, 0, 0, 0) + y_2(0, 1, 0, 0) + y_3(0, 0, 1, -1)$; a basis for the image is the set $\mathcal{B}_{\text{Ima}(F)} = \{(1, 0, 0, 0), (0, 1, 0, 0), (0, 0, 1, -1)\}$.

I M 4) Consider the matrix $\mathbb{U} = \begin{bmatrix} k & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & k \end{bmatrix}$. Knowing that the matrix \mathbb{U} is an orthogonal

matrix, calculate the value of k and find the eigenvalues of matrix \mathbb{U} .

Remember that a matrix \mathbb{U} is a orthogonal matrix if and only if $\mathbb{U} \cdot \mathbb{U}^T = \mathbb{U}^T \cdot \mathbb{U} = \mathbb{I}$, an identity matrix. Also matrix \mathbb{U} is symmetrical, so $\mathbb{U}^T = \mathbb{U}$ and $\mathbb{U} \cdot \mathbb{U}^T = \mathbb{U}^T \cdot \mathbb{U} = \mathbb{U} \cdot \mathbb{U}$.

$$\mathbb{U} \cdot \mathbb{U} = \begin{bmatrix} k & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & k \end{bmatrix} \cdot \begin{bmatrix} k & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & k \end{bmatrix} = \begin{bmatrix} 1+k^2 & 0 & 2k \\ 0 & 1 & 0 \\ 2k & 0 & 1+k^2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ if and}$$

only if $k = 0$; $\mathbb{U} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$. To find the eigenvalues of matrix \mathbb{U} we calculate the

$$\text{characteristic polynomial of the matrix: } P_{\mathbb{U}}(\lambda) = |\lambda \mathbb{I} - \mathbb{U}| = \begin{vmatrix} \lambda & 0 & -1 \\ 0 & \lambda - 1 & 0 \\ -1 & 0 & \lambda \end{vmatrix} =$$

$$(\lambda - 1) \begin{vmatrix} \lambda & -1 \\ -1 & \lambda \end{vmatrix} = (\lambda - 1)(\lambda^2 - 1) = (\lambda - 1)^2(\lambda + 1). \text{ Putting } P_{\mathbb{U}}(\lambda) = 0 \text{ we}$$

find the three eigenvalues of matrix \mathbb{U} : $\lambda_{1,2} = 1, \lambda_3 = -1$.

II M 1) With the equation $f(x, y, z) = xyz + 2xy^2 + 2xz^2 + 3yz = 0$ we can defined in a neighbourhood of point $P(1, -1, 1)$ a function in implicit form. Which type of implicit function can we define? Calculate its first order derivatives.

$f(P) = -1 + 2 + 2 - 3 = 0$, condition is satisfied in point P .

$$\nabla f = (yz + 2y^2 + 2z^2, xz + 4xy + 3z, xy + 4xz + 3y), \nabla f(P) = (3, 0, 0).$$

In point P only $f'_x(P) \neq 0$, thus the proposed condition defines a implicit function

$$(y, z) \mapsto x(y, z) \text{ with } x'_y(-1, 1) = -\frac{f'_y(P)}{f'_x(P)} = 0 \text{ and } x'_z(-1, 1) = -\frac{f'_z(P)}{f'_x(P)} = 0.$$

$(-1, 1)$ is a critical point for function $x(y, z)$.

II M 2) Solve the problem
$$\begin{cases} \text{Max/min } f(x, y) = 3y - x \\ \text{u.c.: } x^2 + y^2 \leq 4 \end{cases}.$$

The function f is a polynomial, continuous function, the admissible region is a disk with center $(0, 0)$ and radius 2, a bounded and closed set, therefore f presents absolute maximum and minimum in the admissible region, constraint is qualified on any point in the circumference $x^2 + y^2 = 4$. The Lagrangian function is

$$\mathcal{L}(x, y, \lambda) = 3y - x - \lambda(x^2 + y^2 - 4) \text{ with}$$

$$\nabla \mathcal{L} = (-1 - 2\lambda x, 3 - 2\lambda y, -(x^2 + y^2 - 4)).$$

I° CASE (free optimization):

$$\begin{cases} \lambda = 0 \\ -1 = 0 \\ 3 = 0 \\ x^2 + y^2 \leq 4 \end{cases} ; \text{System impossible.}$$

II° CASE (constrained optimization):

$$\begin{cases} \lambda \neq 0 \\ -1 - 2\lambda x = 0 \\ 3 - 2\lambda y = 0 \\ x^2 + y^2 = 4 \end{cases} \Rightarrow \begin{cases} \lambda \neq 0 \\ x = -\frac{1}{2\lambda} \\ y = \frac{3}{2\lambda} \\ \left(-\frac{1}{2\lambda}\right)^2 + \left(\frac{3}{2\lambda}\right)^2 = 4 \end{cases} \Rightarrow \begin{cases} \lambda \neq 0 \\ x = -\frac{1}{2\lambda} \\ y = \frac{3}{2\lambda} \\ \frac{10}{4\lambda^2} = 4 \end{cases} \Rightarrow \begin{cases} \lambda \neq 0 \\ x = -\frac{1}{2\lambda} \\ y = \frac{3}{2\lambda} \\ \lambda^2 = \frac{10}{16} \end{cases} \Rightarrow$$

$$\begin{cases} \lambda \neq 0 \\ x = \mp \frac{1}{5}\sqrt{10} \\ y = \pm \frac{3}{5}\sqrt{10} \\ \lambda = \pm \frac{1}{4}\sqrt{10} \end{cases} . \text{ Two critical points, } P_1 = \left(-\frac{1}{5}\sqrt{10}, +\frac{3}{5}\sqrt{10}\right) \text{ the unique}$$

candidate for maximum ($\lambda > 0$), and $P_2 = \left(+\frac{1}{5}\sqrt{10}, -\frac{3}{5}\sqrt{10}\right)$, the unique

candidate for minimum ($\lambda < 0$). $Max f = f(P_1) = 3\left(\frac{3}{5}\sqrt{10}\right) - \left(-\frac{1}{5}\sqrt{10}\right) = 2\sqrt{10}$, $Min f = f(P_2) = 3\left(-\frac{3}{5}\sqrt{10}\right) - \left(\frac{1}{5}\sqrt{10}\right) = -2\sqrt{10} = -Max f$.

II M 3) Given the function $f(x, y) = |2xy|$. Study if the function f is differentiable at point $O(0, 0)$.

Function f is differentiable at point $O(0, 0)$ if exist real numbers a and b such that

$$\lim_{(x, y) \rightarrow (0, 0)} \frac{f(x, y) - f(0, 0) - (ax + by)}{\sqrt{x^2 + y^2}} = 0. \text{ Using polar coordinates we have}$$

$$\lim_{\rho \rightarrow 0} \frac{|2\rho \cos \theta \cdot \rho \sin \theta| - (a\rho \cos \theta + b\rho \sin \theta)}{\sqrt{(\rho \cos \theta)^2 + (\rho \sin \theta)^2}} =$$

$$\lim_{\rho \rightarrow 0} \frac{2\rho^2 |\cos \theta \cdot \sin \theta| - \rho(a \cos \theta + b \sin \theta)}{\rho} =$$

$\lim_{\rho \rightarrow 0} 2\rho |\cos \theta \cdot \sin \theta| - (a \cos \theta + b \sin \theta)$. From the last limit we can observe that a necessary condition such that the limit is zero is $a = b = 0$ and so our limit can be written as: $\lim_{\rho \rightarrow 0} 2\rho |\cos \theta \cdot \sin \theta| = 0$. To conclude the exercise we can prove that the

convergence is uniformly respect θ ; for this goal note that $|2\rho |\cos \theta \cdot \sin \theta|| = \rho |2 \cdot \sin \theta \cdot \cos \theta| = \rho |\sin 2\theta| \leq \rho$, convergence is uniformly.

II M 4) Given the function $f(x, y, z) = x^3 - y^3 - z^3 - 3x + 12yz$, find its critical points and study their nature.

$$\nabla f = (3x^2 - 3, -3y^2 + 12z, -3z^2 + 12y).$$

FOC:

$$\begin{cases} 3x^2 - 3 = 0 \\ -3y^2 + 12z = 0 \\ -3z^2 + 12y = 0 \end{cases} \Rightarrow \begin{cases} 3x^2 = 3 \\ 12z = 3y^2 \\ -3z^2 + 12y = 0 \end{cases} \Rightarrow \begin{cases} x^2 = 1 \\ z = \frac{1}{4}y^2 \\ -3\left(\frac{1}{4}y^2\right)^2 + 12y = 0 \end{cases} \Rightarrow$$

$$\begin{cases} x = \pm 1 \\ z = \frac{1}{4}y^2 \\ -\frac{3}{16}y^4 + 12y = 0 \end{cases} \Rightarrow \begin{cases} x = \pm 1 \\ z = \frac{1}{4}y^2 \\ \frac{192y - 3y^4}{16} = 0 \end{cases} \Rightarrow \begin{cases} x = \pm 1 \\ z = \frac{1}{4}y^2 \\ 3y(64 - y^3) = 0 \end{cases}; \text{ if } y = 0 \text{ then } z = 0,$$

otherwise if $64 - y^3 = 0$ we get $y = 4$ and $z = 4$. Four critical points:

$$P_{1,2} = (\pm 1, 0, 0) \text{ and } P_{3,4} = (\pm 1, 4, 4).$$

SOC:

$$\mathcal{H}_f = \begin{bmatrix} 6x & 0 & 0 \\ 0 & -6y & 12 \\ 0 & 12 & -6z \end{bmatrix}, \text{ with } \mathcal{H}_f^1 = 6x, \mathcal{H}_f^2 = \begin{vmatrix} 6x & 0 \\ 0 & -6y \end{vmatrix} = -36xy \text{ and}$$

$$\mathcal{H}_f^3 = \begin{vmatrix} 6x & 0 & 0 \\ 0 & -6y & 12 \\ 0 & 12 & -6z \end{vmatrix} = 6x \begin{vmatrix} -6y & 12 \\ 12 & -6z \end{vmatrix} = 6x(36yz - 144) = 216x(yz - 4).$$

For the sign sequence in the four points we get:

$$\mathcal{H}_f^1(P_1) = 6 > 0, \mathcal{H}_f^2(P_1) = 0, \mathcal{H}_f^3(P_1) = -864 < 0; P_1 \text{ saddle point, because}$$

$\mathcal{H}_f^1(P_1)$ and $\mathcal{H}_f^3(P_1)$ have opposite sign;

$$\mathcal{H}_f^1(P_2) = -6 < 0, \mathcal{H}_f^2(P_2) = 0, \mathcal{H}_f^3(P_2) = 864 > 0; P_2 \text{ saddle point;}$$

$$\mathcal{H}_f^1(P_3) = 6 > 0, \mathcal{H}_f^2(P_3) = -144 < 0, \mathcal{H}_f^3(P_3) = 2592 > 0; P_3 \text{ saddle point,}$$

because $\mathcal{H}_f^2(P_3)$ is negative;

$\mathcal{H}_f^1(P_4) = -6 < 0, \mathcal{H}_f^2(P_4) = 144 > 0, \mathcal{H}_f^3(P_4) = -2592 < 0; P_4$ point of maximum, because the odd principal minors are negative and the unique even principal minor is positive.